

Poster ID# **TUE-PM-201**

# Learning Partial Correlation based Deep Visual Representation for Image Classification



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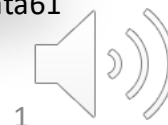
Luping Zhou  
USyD



Peyman Moghadam  
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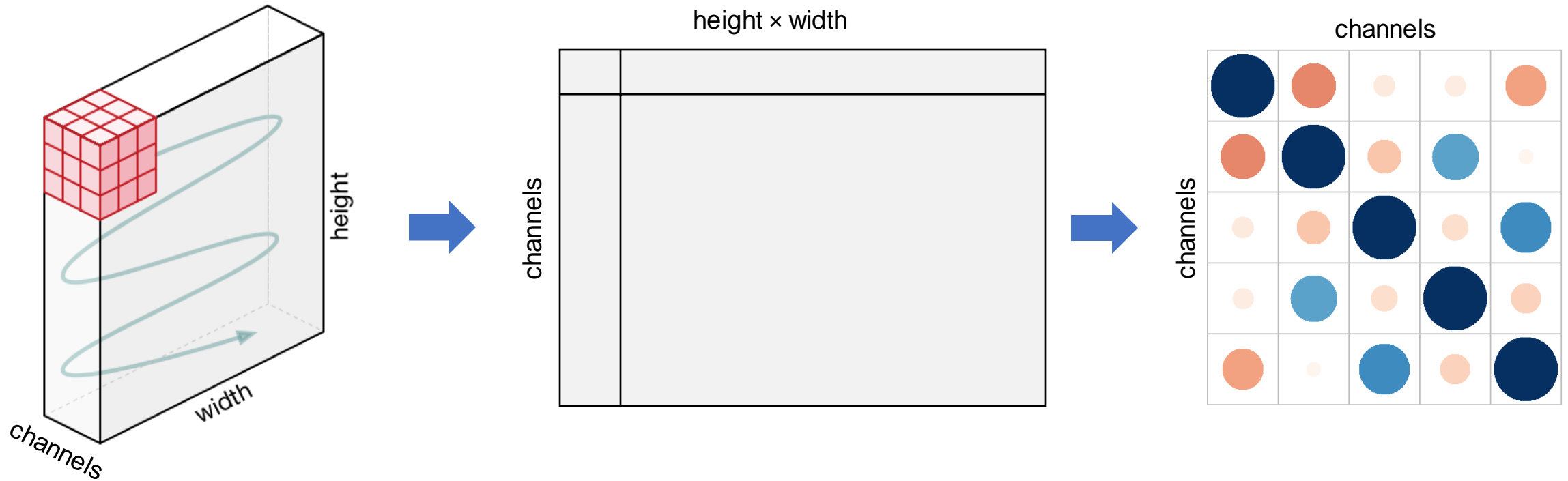


Changming Sun  
CSIRO Data61





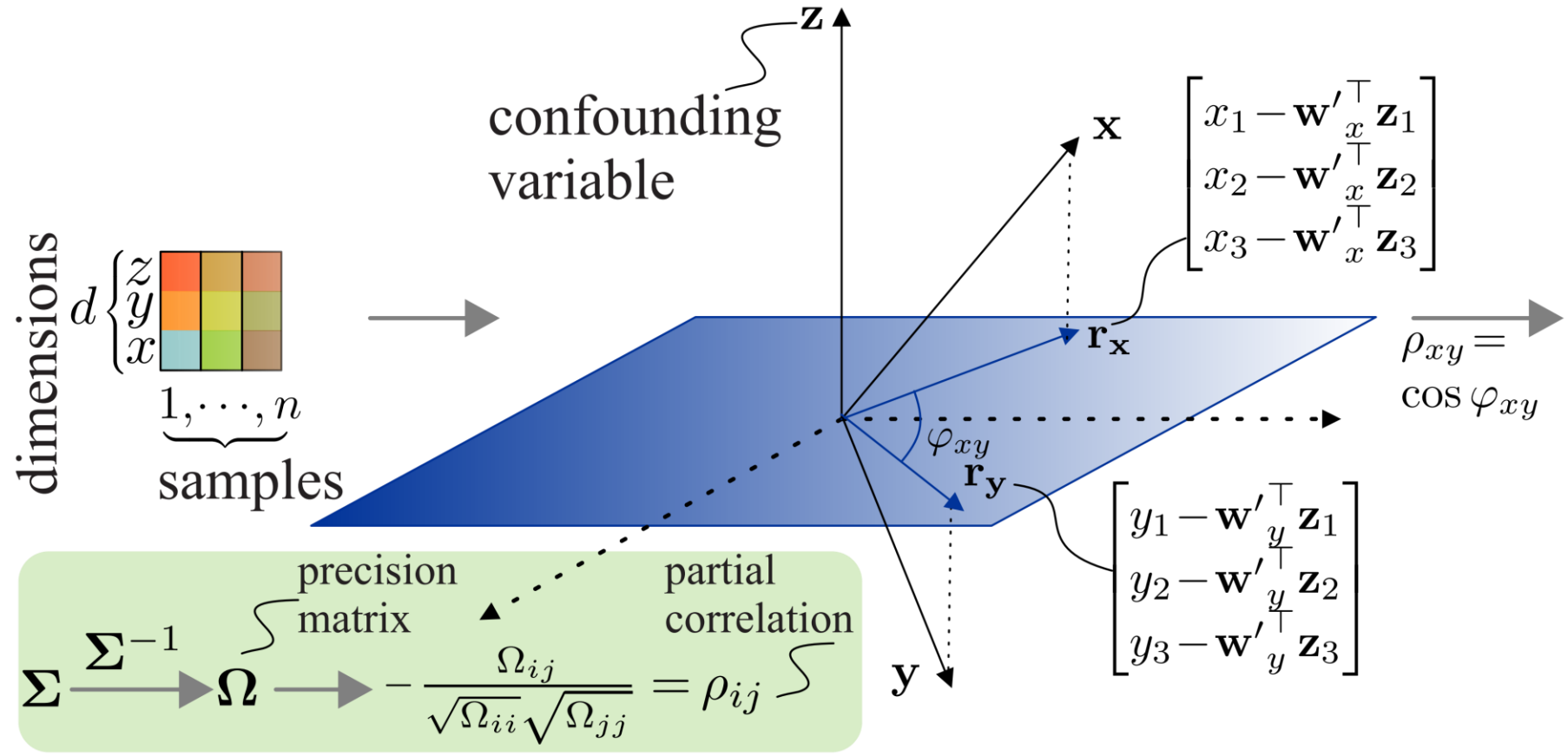
# Pairwise Correlation Based Representation



Example: covariance matrix based visual representation.

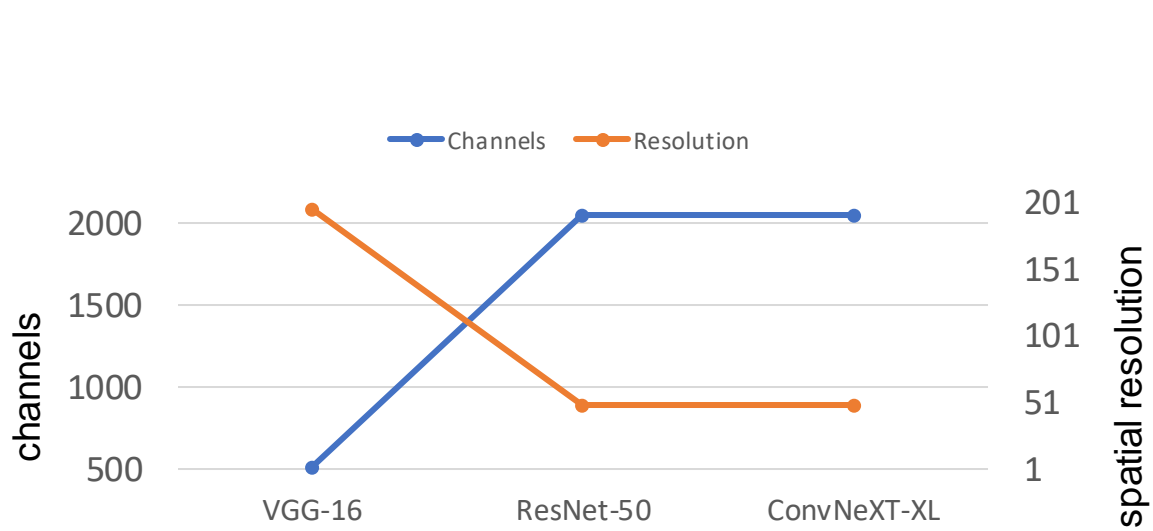


# Confounding Effect in Pairwise Correlation

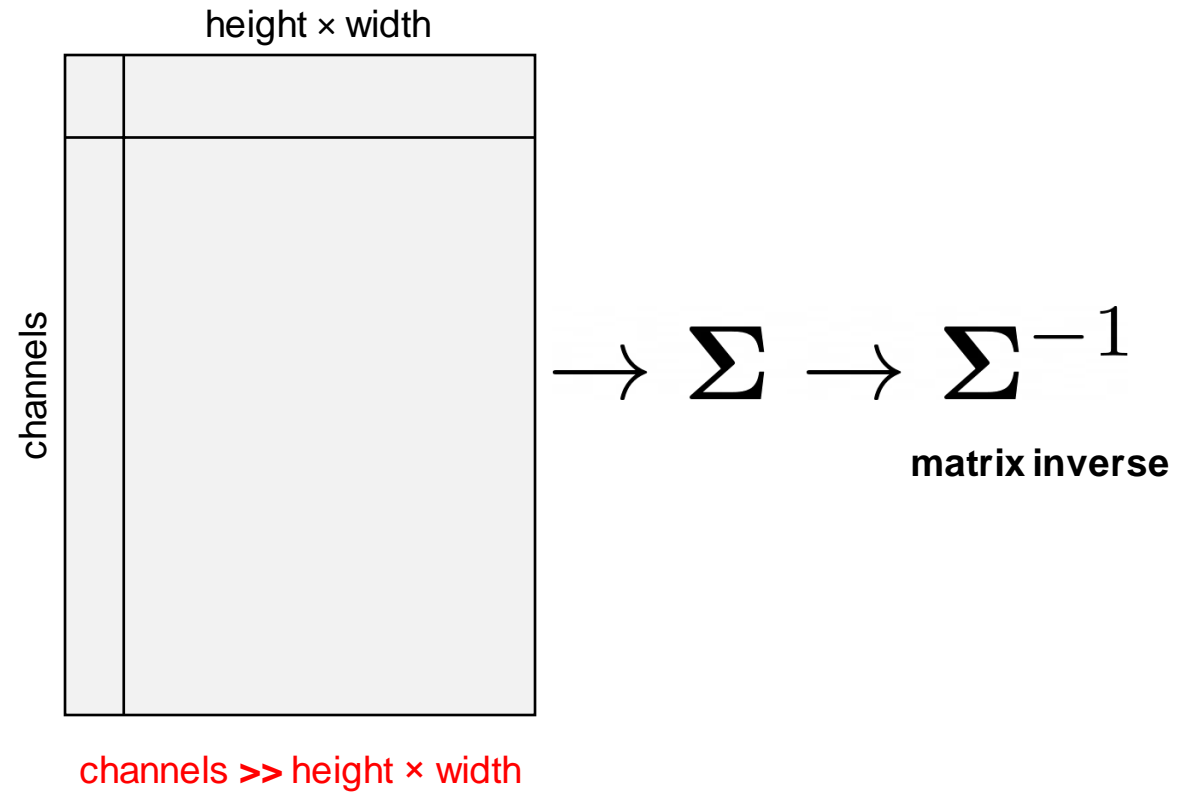


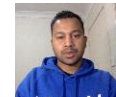


# Partial Correlation Estimation from CNN



Number of channels vs. their resolutions in recent CNNs.



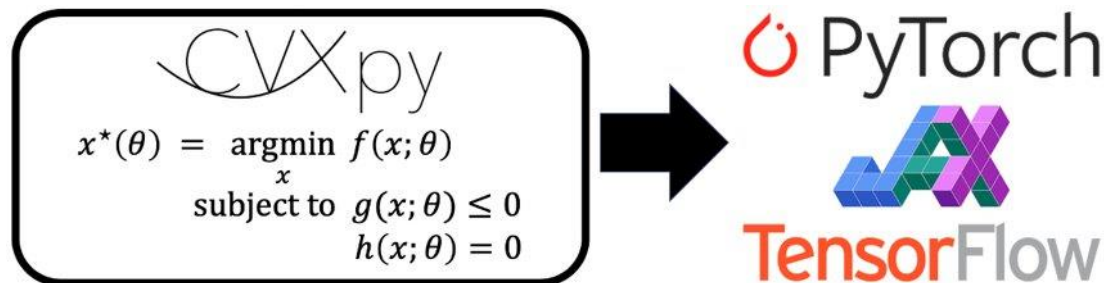


# Sparse Inverse Covariance Estimate (SICE)

SICE is defined as follows:

$$\mathbf{S}^* = \arg \max_{\mathbf{S} > 0} \log \det(\mathbf{S}) - \text{trace}(\mathbf{\Sigma} \mathbf{S}) - \lambda \|\mathbf{S}\|_1$$

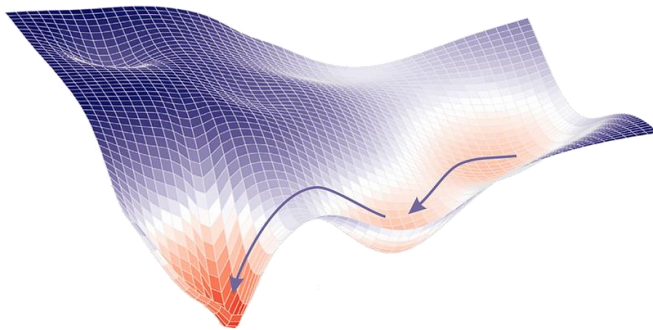
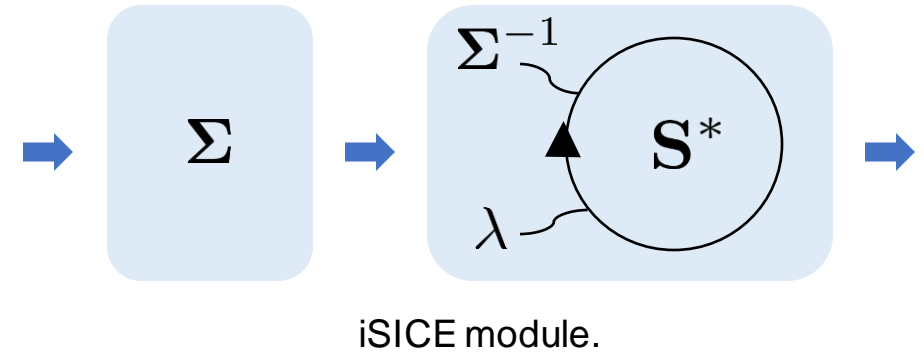
where  $\mathbf{\Sigma}$  is a sample-based covariance matrix, and  $\det(\cdot)$ ,  $\text{trace}(\cdot)$  and  $\|\cdot\|_1$  denote the determinant, trace and  $\ell_1$ -norm of a vectorization of matrix, respectively.



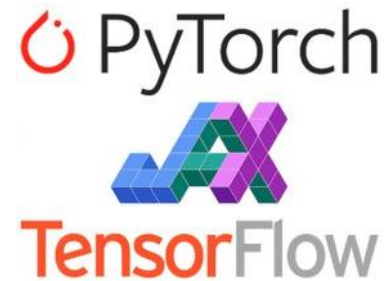


# Proposed Iterative SICE (iSICE)

$$\begin{aligned} \frac{\partial J}{\partial \mathbf{S}} &= \frac{\partial}{\partial \mathbf{S}} \log \det(\mathbf{S}) - \frac{\partial}{\partial \mathbf{S}} \text{trace}(\mathbf{\Sigma} \mathbf{S}) - \lambda \frac{\partial}{\partial \mathbf{S}} \|\mathbf{S}\|_1 \\ &= \mathbf{S}^{-1} - \mathbf{\Sigma} - \lambda \left( \frac{\partial}{\partial \mathbf{S}} \mathbf{S}^+ - \frac{\partial}{\partial \mathbf{S}} \mathbf{S}^- \right) \\ &= \mathbf{S}^{-1} - \mathbf{\Sigma} - \lambda (\text{sign}(\mathbf{S}^+) - \text{sign}(\mathbf{S}^-)), \end{aligned}$$

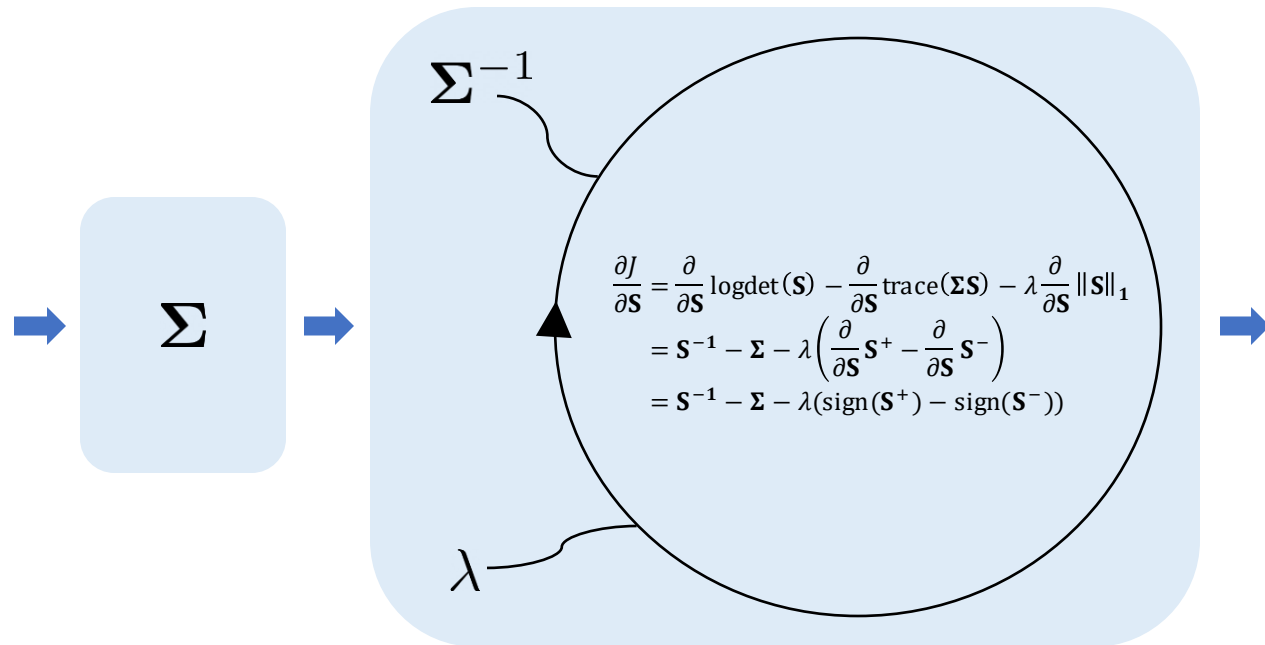


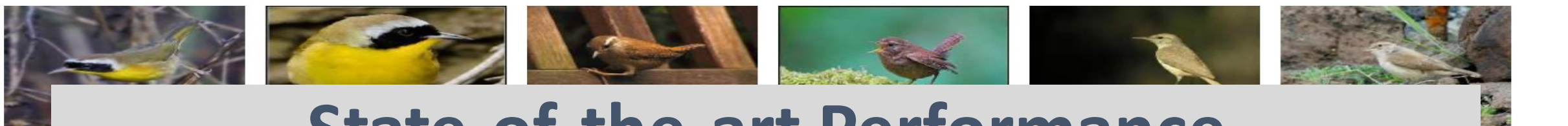
Stochastic gradient descend (SGD) based optimisation.





# Partial Correlation Representaion





# State-of-the-art Performance

**MIT Indoor dataset**

**CUB-200 dataset**

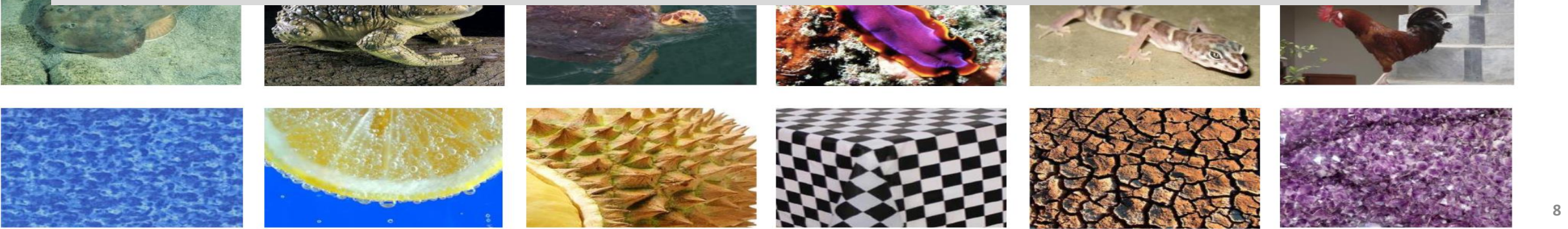
**FGVC Aircraft dataset**

**Stanford Cars dataset**

**ImageNet100/mini-ImageNet datasets**

**iNaturalist dataset**

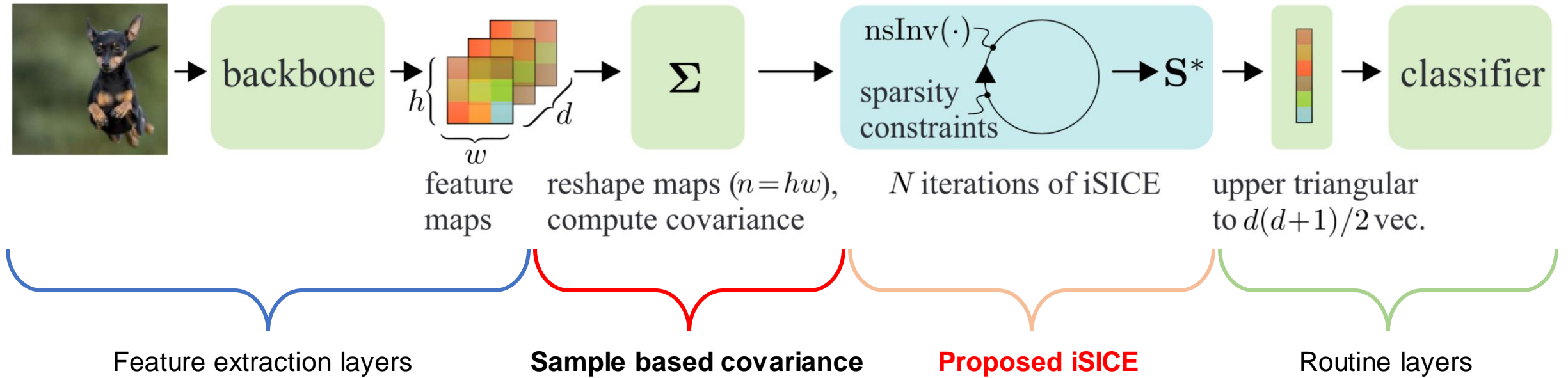
**DTD dataset**







# iSICE Integration With CNN



Three important iSICE parameters 1) **Sparsity** 2) **Number of iterations** and 3) **Learning rate**.

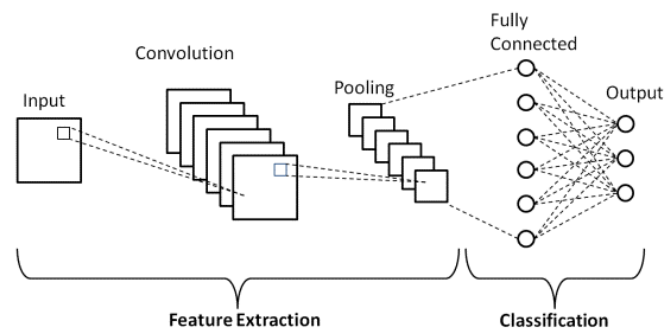


# Implementation Details

## Implementation Library

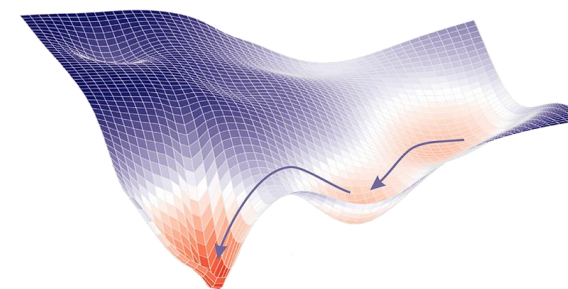


## Network Architectures



- VGG-16/19
- ResNet-50/101
- ResNeXt-50/101
- ConvNeXt-T/B
- Swin-T/B

## Optimiser



AdamW



# Evaluation Datasets

Dataset	Total classes	Total images	Predefined protocol		Major difficulty
			Training images	Testing images	
MIT Indoor	67	6,700	5,360	1,340	difficult environment
Birds	200	11,788	5,994	5,794	subtle class difference
Aircraft	100	10,000	6,600	3,400	subtle class difference
Cars	196	16,185	8,144	8,041	cluttered background
DTD	47	5,640	4512	1128	complex structure
iNaturalist	5,089	675,170	579,184	95,986	class imbalance
mini-ImageNet	100	60,000	54,000	6,000	difficult environment
ImageNet100	100	1,35,000	130,000	5,000	difficult environment



# Experimental Results

iSICE Hyper-parameter Selection, *e.g.*, sparsity.

Dataset	Backbone	iSQRT-COV [23]	Precision $\Omega$	iSICE							Mean $\pm$ Std. (iSICE)
				Sparsity constant $\lambda$							
				1.0	0.5	0.1	0.01	0.001	0.0001	0.00001	
MIT	VGG-16	76.12	<b>80.15</b>	77.46	78.13	78.13	78.66	78.58	78.96	78.96	78.41 $\pm$ 0.54
	ResNet-50	78.81	80.75	78.43	80.75	80.45	80.52	80.90	80.37	<b>81.34</b>	80.39 $\pm$ 0.93
Airplane	VGG-16	90.01	89.44	92.26	92.71	92.77	92.23	<b>92.83</b>	92.74	92.44	92.56 $\pm$ 0.25
	ResNet-50	90.88	91.15	<b>92.89</b>	92.65	<b>92.89</b>	92.74	92.83	92.56	92.56	92.73 $\pm$ 0.14
Birds	VGG-16	84.47	83.36	86.04	86.47	86.35	<b>86.52</b>	85.59	86.31	86.28	86.22 $\pm$ 0.32
	ResNet-50	84.26	84.67	84.62	85.16	85.30	85.90	<b>86.05</b>	85.90	85.59	85.50 $\pm$ 0.51
Cars	VGG-16	91.21	92.04	93.60	93.98	<b>94.06</b>	94.03	93.88	93.91	93.50	93.85 $\pm$ 0.22
	ResNet-50	92.13	91.99	93.01	93.36	93.69	93.51	93.22	<b>93.72</b>	93.40	93.41 $\pm$ 0.25



# Experimental Results

iSICE vs. its covariance counterparts on scene, fine-grained and generic image dataset.

Method	Matrix Dim.	MIT		Airplane		Birds		Cars		Average	
		VGG	ResNet	VGG	ResNet	VGG	ResNet	VGG	ResNet	VGG	ResNet
iSQRT-COV	256 × 256	76.1	78.8	90.0	90.9	84.5	84.3	91.2	92.1	85.5	86.5
	512 × 512	76.9	<b>82.8</b>	91.5	91.1	85.0	84.5	92.2	92.1	86.4	87.6
Precision $\Omega$	256 × 256	<b>80.2</b>	<b>80.8</b>	89.4	91.2	83.4	84.7	92.0	92.0	86.3	87.1
	512 × 512	80.7	82.7	90.1	91.5	84.9	84.0	92.5	92.6	87.0	87.7
SICE	128 × 128	71.0	73.1	85.5	86.9	77.3	78.0	87.0	87.9	80.2	81.5
	256 × 256	73.7	75.4	87.9	89.2	79.7	80.3	89.5	89.3	82.7	83.6
iSICE	256 × 256	78.7	80.5	<b>92.2</b>	<b>92.7</b>	<b>86.5</b>	<b>85.9</b>	<b>94.0</b>	<b>93.5</b>	<b>87.9</b>	<b>88.2</b>
	512 × 512	<b>81.1</b>	81.7	<b>92.9</b>	<b>92.6</b>	<b>86.8</b>	<b>86.0</b>	<b>94.6</b>	<b>93.8</b>	<b>88.9</b>	<b>88.5</b>

ImageNet-100 dataset

Method	Backbone	Top-1	Top-5
GAP [13]		71.0/69.5	90.9/88.9
iSQRT-COV [23]	ResNet-50/	71.5/70.2	90.5/89.7
Precision $\Omega$	VGG-16	71.1/71.0	90.1/90.1
<b>iSICE</b>		<b>74.8/73.4</b>	<b>92.0/91.8</b>



# Experimental Results

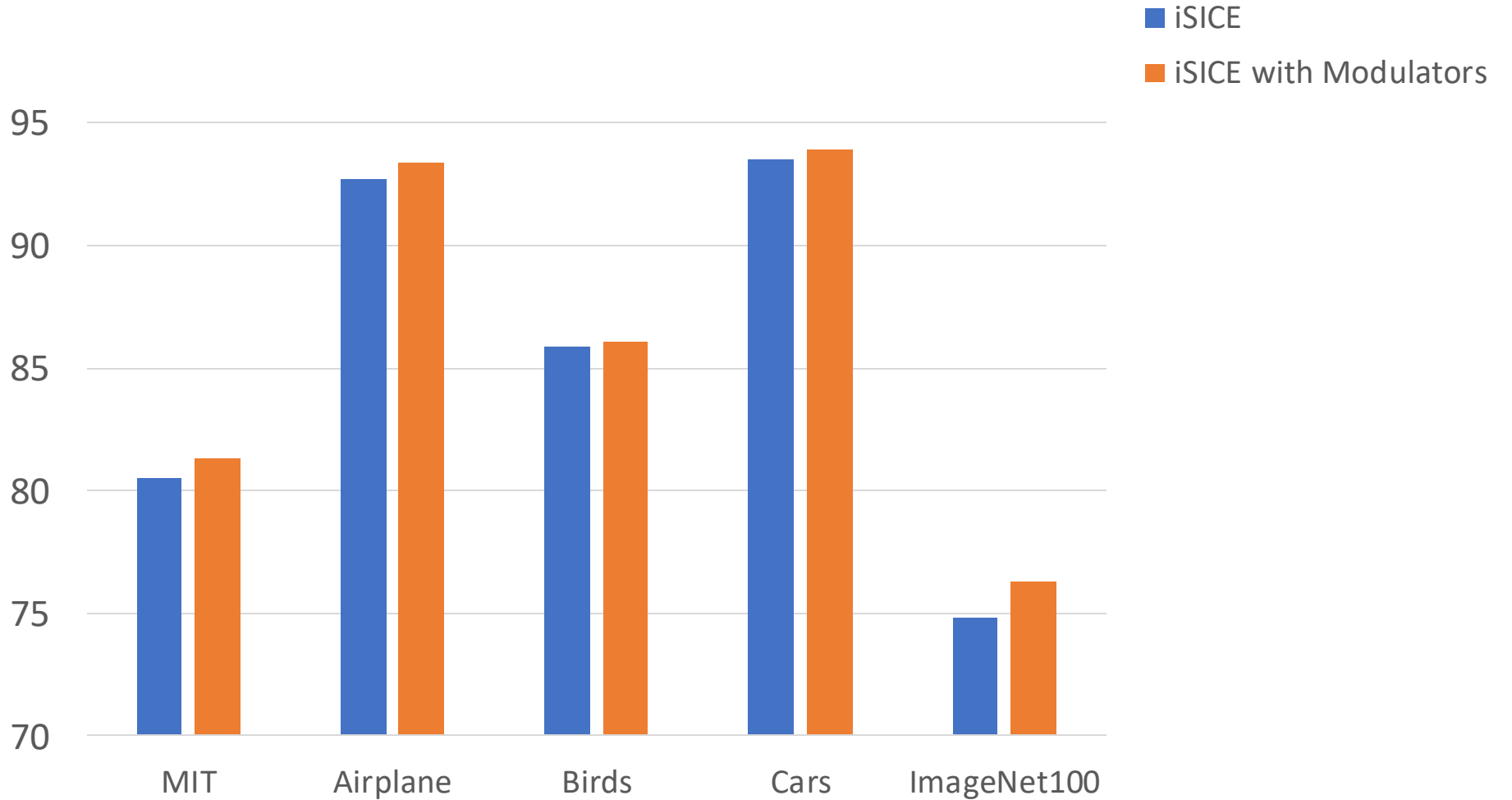
iSICE vs. its covariance counterparts on various datasets and backbones.

Method	Backbone	MIT	Airplane	Birds	Cars	DTD	iNatuurlist	mini-ImageNet
GAP [37]		–	76.6	70.4	79.8	–	–	–
NetVLAD [2]		–	81.8	81.6	88.6	–	–	–
NetFV [28]		–	79.0	79.9	86.2	–	–	–
BCNN [27]		77.6	83.9	84.0	90.6	70.6	–	–
CBP [11]		76.2	84.1	84.3	91.2	67.7	–	–
LRBP [17]		–	87.3	84.2	90.9	–	–	–
KP [6]		–	86.9	86.2	92.4	–	–	–
HIHCA [4]		–	88.3	85.3	91.7	–	–	–
Improved BCNN [25]		–	88.5	85.8	92.0	–	–	–
SMSO [46]	VGG-16	79.5	–	85.0	–	–	–	–
MPN-COV [43] (reproduced)		–	86.1	82.9	89.8	–	–	–
iSQRT-COV [23] (reproduced)		76.1	90.0	84.5	91.2	71.3	56.2	76.2
DeepCOV [9]		79.2	88.7	85.4	91.7	–	–	–
DeepKSPD [9]		<b>81.0</b>	90.0	84.8	91.6	–	–	–
RUN [47]		80.5	91.0	85.7	–	–	–	–
FCBN [48]		80.3	90.5	85.5	–	–	–	–
TKPF [49]		80.5	91.4	86.0	–	–	–	–
Precision $\Omega$		80.2	89.4	83.4	92.0	74.0	57.9	81.0
iSICE (ours)		<b>78.7</b>	<b>92.2</b>	<b>86.5</b>	<b>94.0</b>	<b>74.7</b>	<b>59.8</b>	<b>78.7</b>
CBP [11]		–	81.6	81.6	88.6	–	–	–
KP [6]		–	85.7	84.7	91.1	–	–	–
SMSO [46]		79.7	–	85.8	–	–	–	–
iSQRT-COV [23] (reproduced)		78.8	90.9	84.3	92.1	73.0	57.7	70.7
DeepCOV-ResNet [34]	ResNet-50	83.4	83.9	<b>86.0</b>	85.0	–	–	–
TKPF [49]		<b>84.1</b>	92.1	85.7	–	–	–	–
Precision $\Omega$		80.8	91.2	84.7	92.0	73.7	59.6	65.6
iSICE (ours)		<b>80.5</b>	<b>92.7</b>	<b>85.9</b>	<b>93.5</b>	<b>75.7</b>	<b>60.7</b>	<b>72.0</b>
iSQRT-COV [23]	VGG-19	76.3	90.3	84.1	91.4	71.8	56.9	75.4
Precision $\Omega$		79.6	91.1	83.2	92.2	74.2	57.3	73.8
iSICE (ours)		<b>80.6</b>	<b>92.5</b>	<b>86.6</b>	<b>93.9</b>	<b>74.9</b>	<b>59.6</b>	77.1
iSQRT-COV [23]	ResNet-101	79.3	91.0	84.4	92.3	73.0	70.6	73.9
Precision $\Omega$		77.9	90.1	83.3	91.4	71.2	69.8	73.0
iSICE (ours)		<b>81.0</b>	<b>92.9</b>	<b>86.6</b>	<b>93.6</b>	<b>75.4</b>	<b>72.0</b>	<b>78.0</b>
iSQRT-COV [23]	ResNeXt-101	81.6	91.3	86.2	92.4	75.7	72.2	76.1
Precision $\Omega$		85.7	90.2	84.6	89.9	76.9	72.3	77.6
iSICE (ours)		<b>86.3</b>	<b>94.6</b>	<b>87.2</b>	<b>94.5</b>	<b>78.7</b>	<b>73.8</b>	<b>81.0</b>
iSQRT-COV [23]	ConvNext-T	77.8	88.1	83.5	89.4	84.7	61.5	82.0
Precision $\Omega$		78.5	81.2	83.7	92.2	83.9	59.3	83.6
iSICE (ours)		<b>85.4</b>	<b>90.4</b>	<b>86.7</b>	<b>93.1</b>	<b>88.9</b>	<b>65.0</b>	<b>85.1</b>
iSQRT-COV [23]	Swin-T	82.1	87.6	85.1	89.7	86.1	58.1	67.7
Precision $\Omega$		82.5	88.2	84.9	90.5	86.5	59.1	65.6
iSICE (ours)		<b>85.9</b>	<b>89.6</b>	<b>86.5</b>	<b>91.3</b>	<b>88.3</b>	<b>61.9</b>	<b>69.1</b>
iSQRT-COV [23]	Swin-B	86.6	91.3	88.0	92.0	79.4	69.7	64.9
Precision $\Omega$		87.0	90.7	87.7	93.1	<b>80.1</b>	67.3	66.4
iSICE (ours)		<b>87.6</b>	<b>92.9</b>	<b>88.3</b>	<b>93.3</b>	79.8	<b>72.4</b>	<b>68.4</b>



# Experimental Results

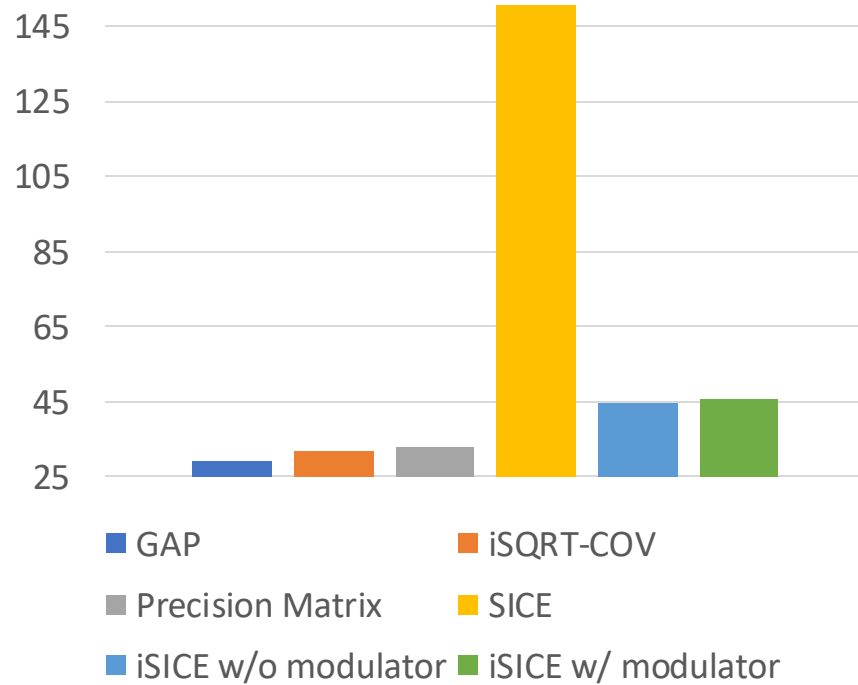
iSICE with learning rate and sparsity modulators.



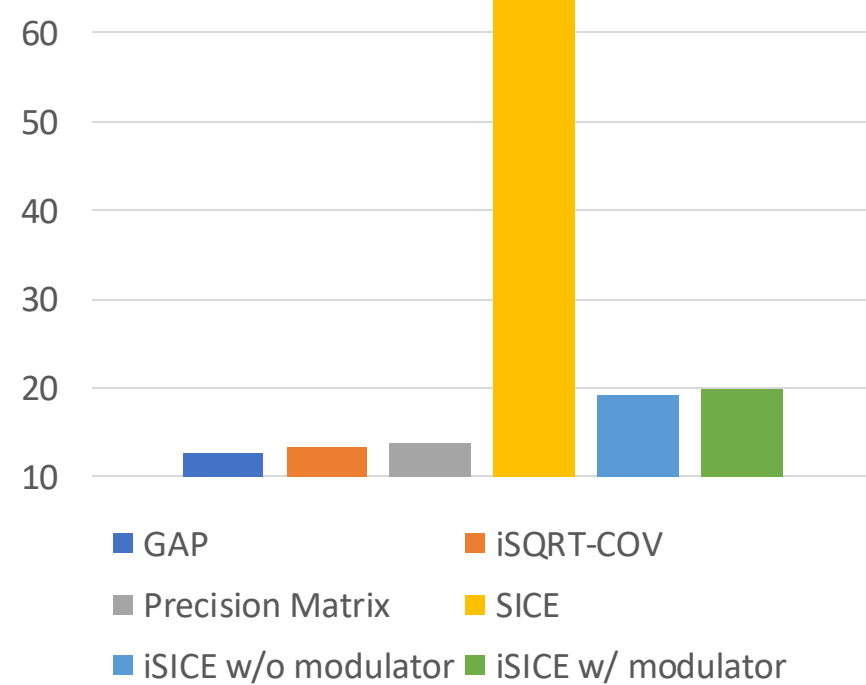


# Computation Cost

Time/batch (in secs.)



Time/epoch (in mins.)







# Visualisation of Learned Features

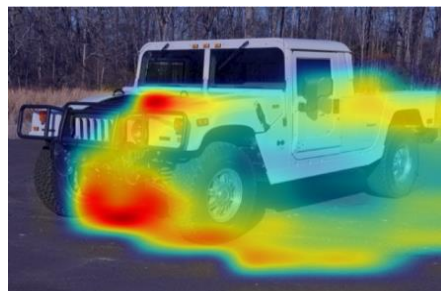
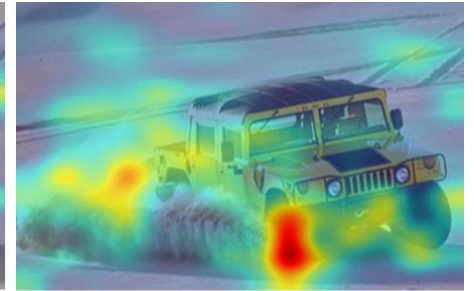
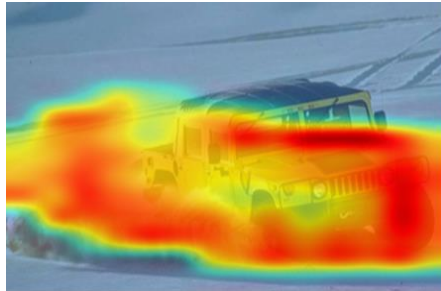
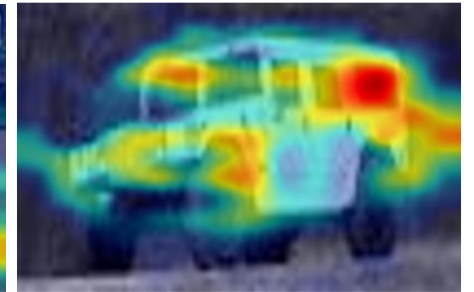
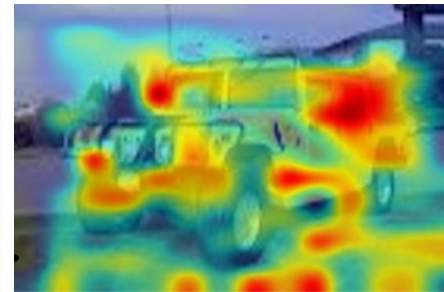
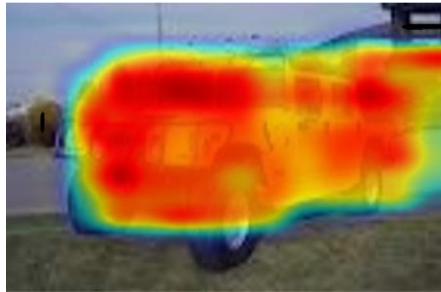
Input Image

GAP

iSQRT-COV

Precision Matrix

iSICE





# Visit our project website for code and more details



<https://csiro-robotics.github.io/iSICE>



**GitHub**

<https://github.com/csiro-robotics/iSICE>



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