

# NeuralDome: A Neural Modeling Pipeline on Multi-View Human-Object Interactions

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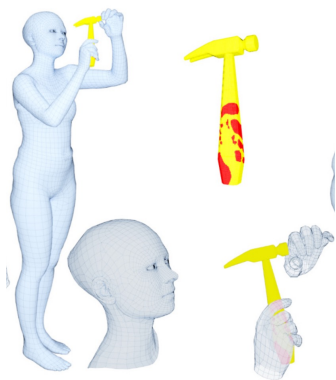


中国科学院大学  
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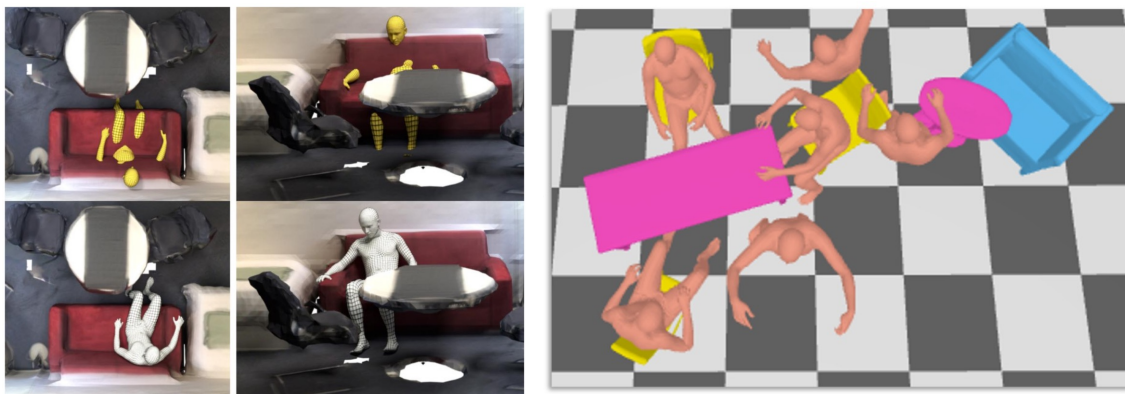
# **Related Work**

w/o RGB



GRAB

Static Scene Only



PROX

MOVER

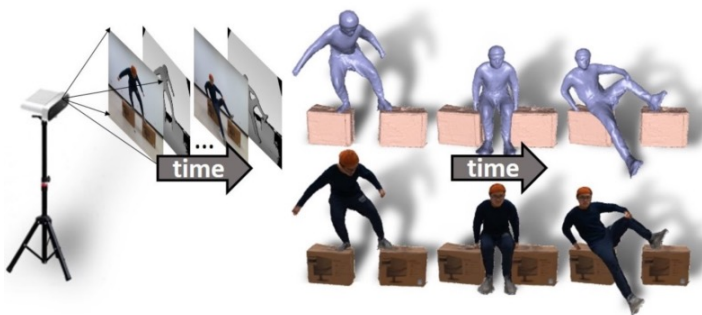
Capturing Only



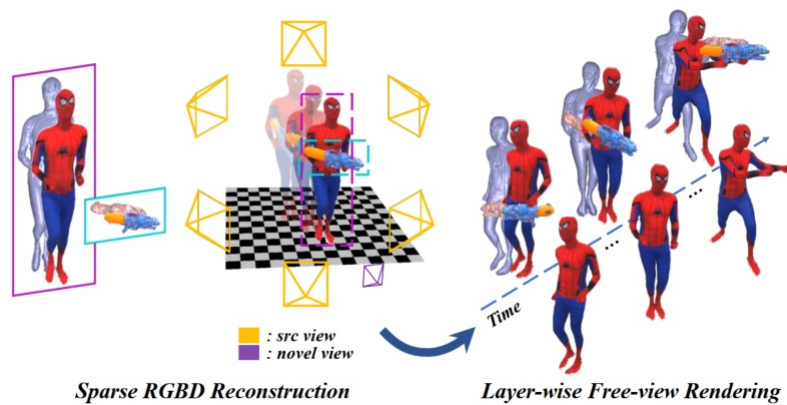
BEHAVE

InterCap

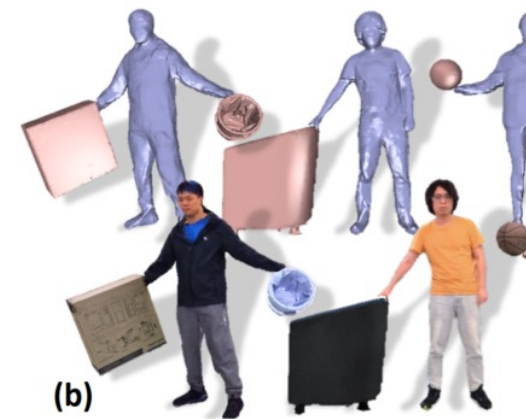
w/o Dense View Recording



RobustFusion



NeuralHOFusion

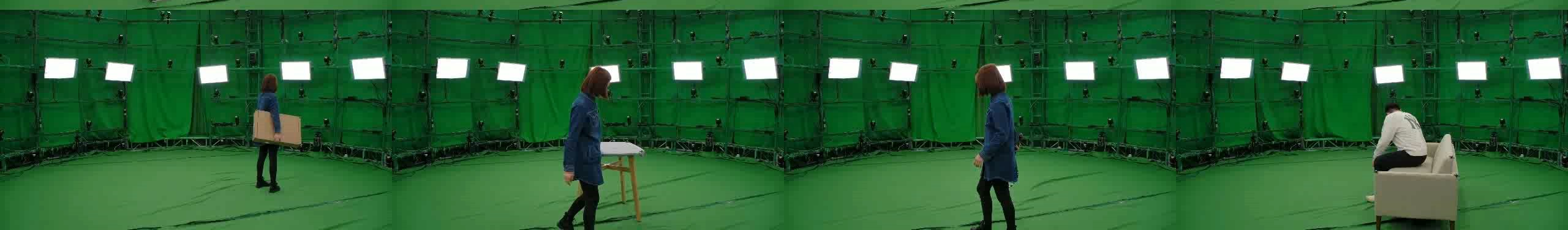
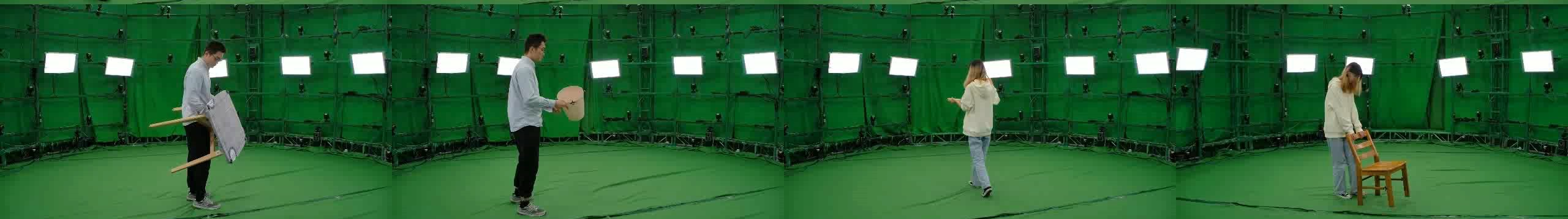
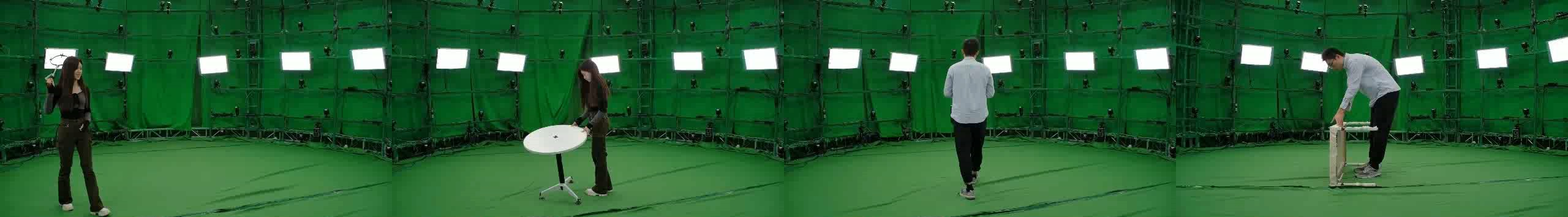


Neural Free-Viewpoint

# **HODome Dataset**

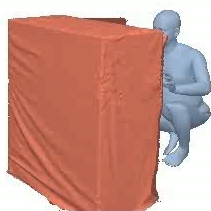




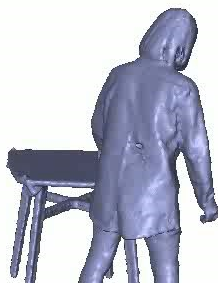
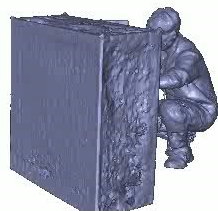
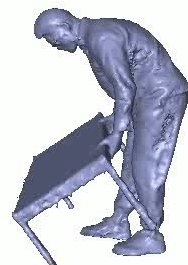
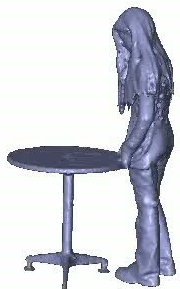


**Mocap**





# Geometry

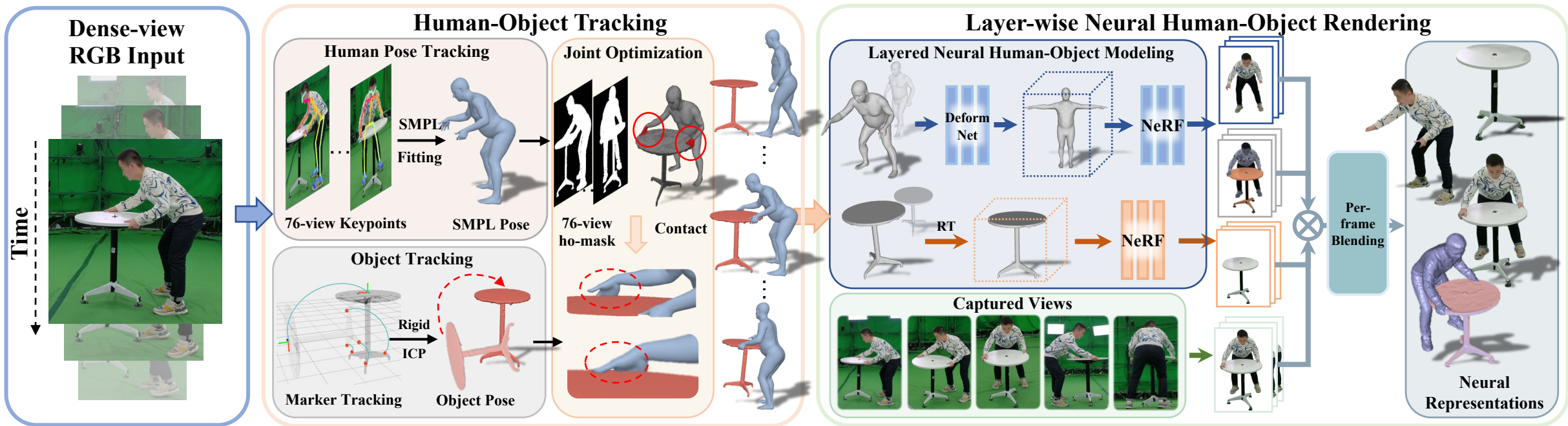


**Novel view**





# **NuralDome Pipeline**

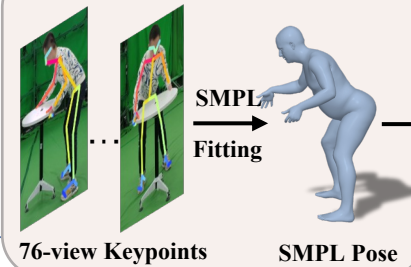


### Dense-view RGB Input

Time

### Human-Object Tracking

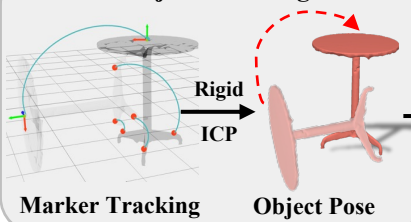
#### Human Pose Tracking



#### Joint Optimization

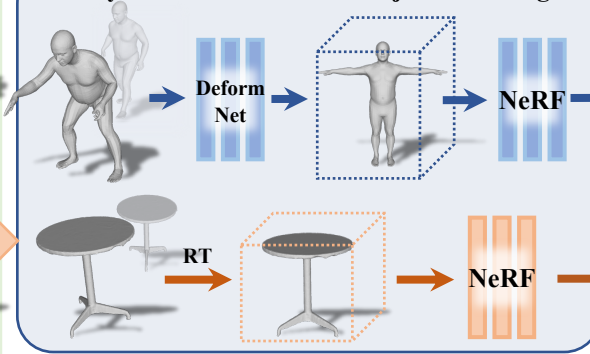


#### Object Tracking



### Layer-wise Neural Human-Object Rendering

#### Layered Neural Human-Object Modeling



#### Captured Views



Per-frame Blending

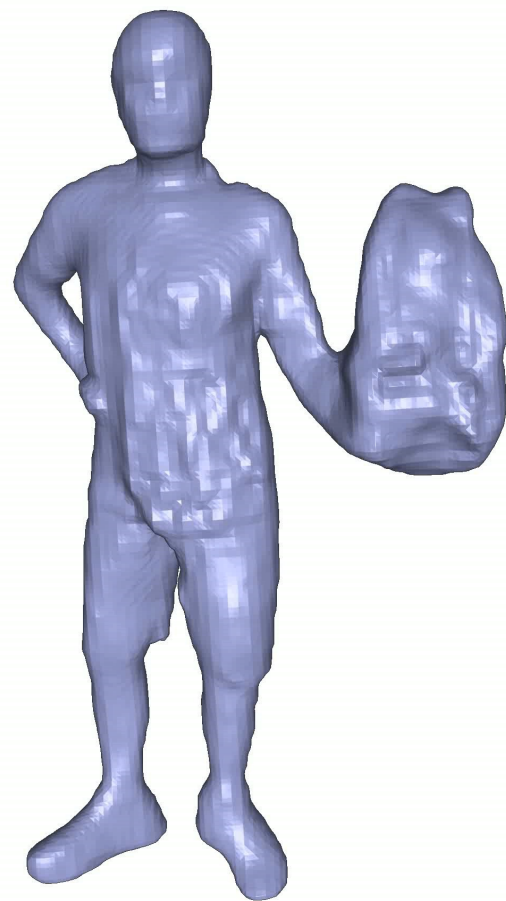
Neural Representations

# **Evaluation**

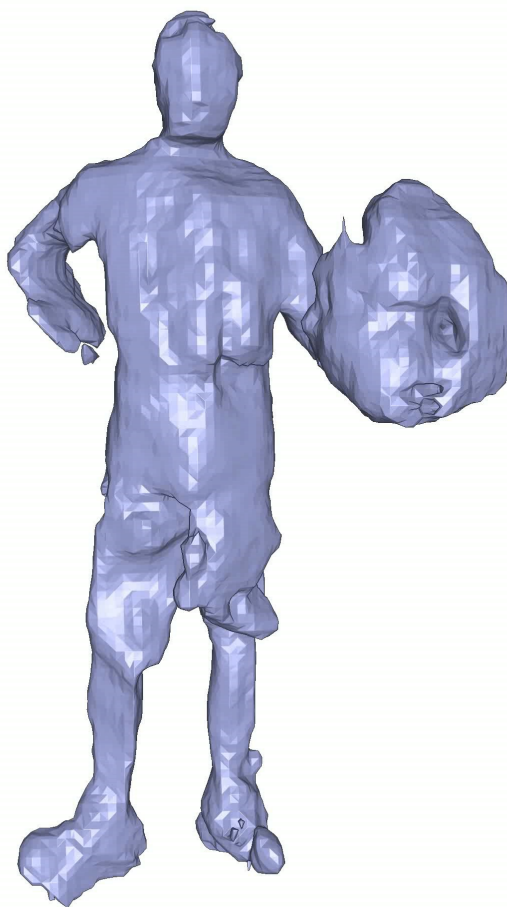


# **Geometry Reconstruction Benchmark**

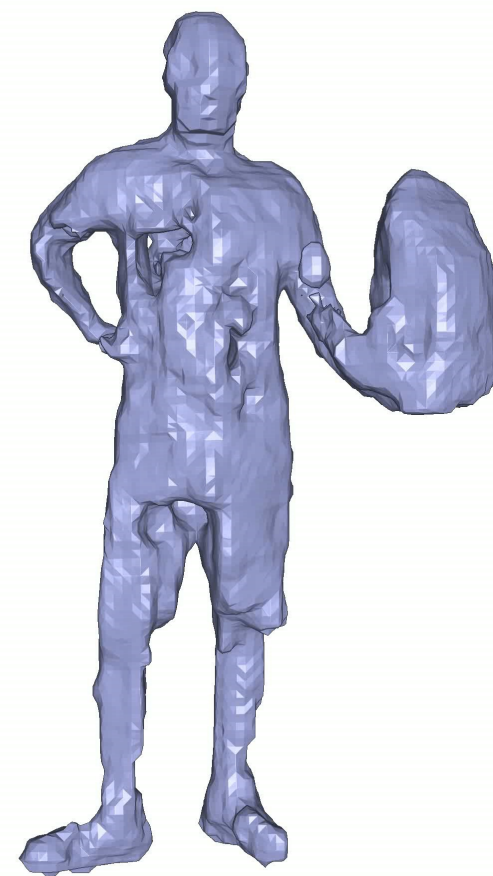




**PIFU-Origin**



**Monocular  
PIFU-Trained**



**Six View  
PIFU-Trained**

# **Human-object Rendering Benchmark**



**NeuRay**



**IBRNet**



**NeuralHOIFVV**

**Thank you for watching!**