



AdaShift: Learning Discriminative Self-Gated Neural Feature Activation With an Adaptive Shift Factor

Sudong Cai

Graduate School of Informatics, Kyoto University

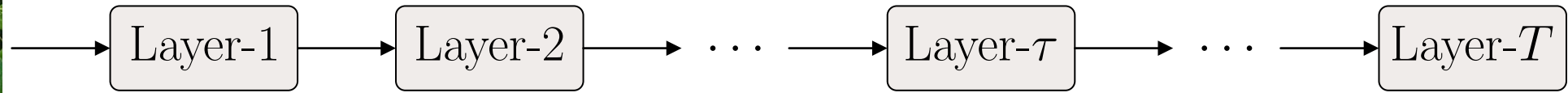
京都大学

KYOTO UNIVERSITY



Introduction

- Preliminaries



Comprehensive scoring
(relaxed similarity)

$$\tilde{x} = \langle \mathbf{w}, \mathbf{x} \rangle$$

Neural Activation:
Feature selection by weights

$$\phi(\tilde{x}) = \rho(\tilde{x}) \cdot \tilde{x}$$

Importance score (weight)

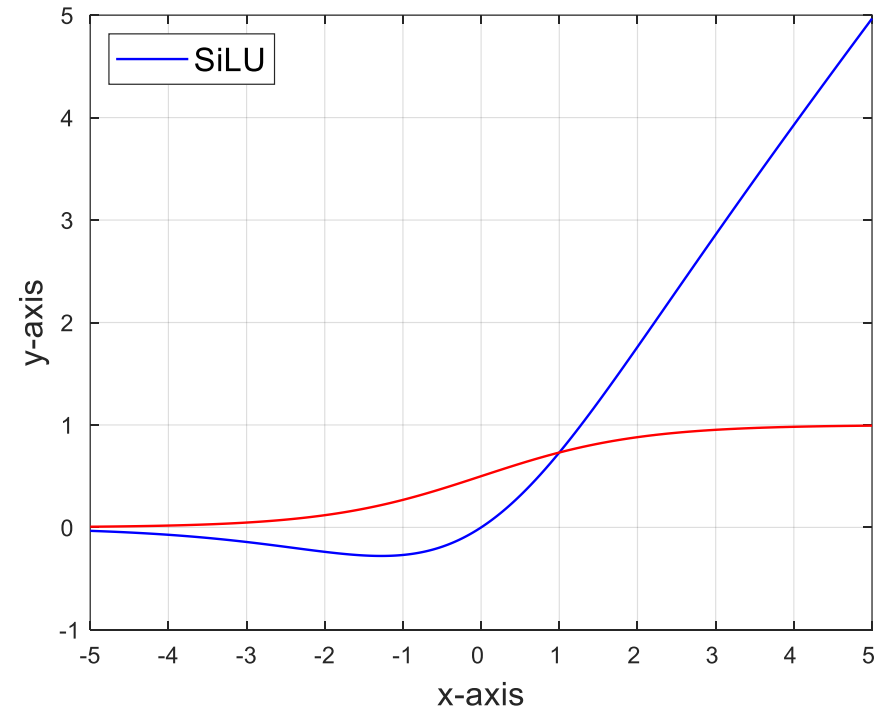
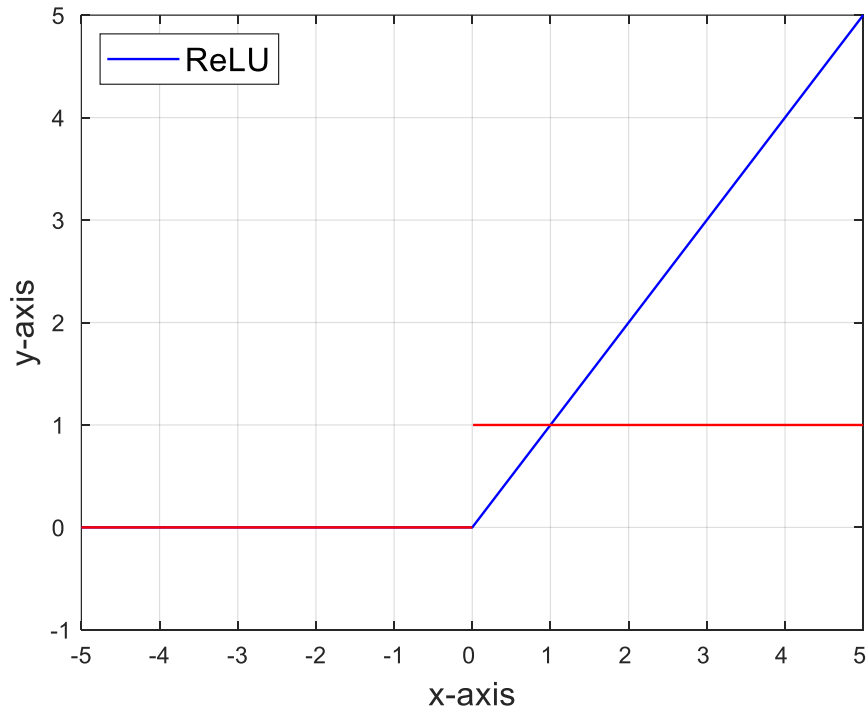
Introduction

- Self-Gated Activation Functions

$$\rho(\tilde{x}) = \begin{cases} 1, & \tilde{x} > 0; \\ 0, & \tilde{x} \leq 0. \end{cases}$$

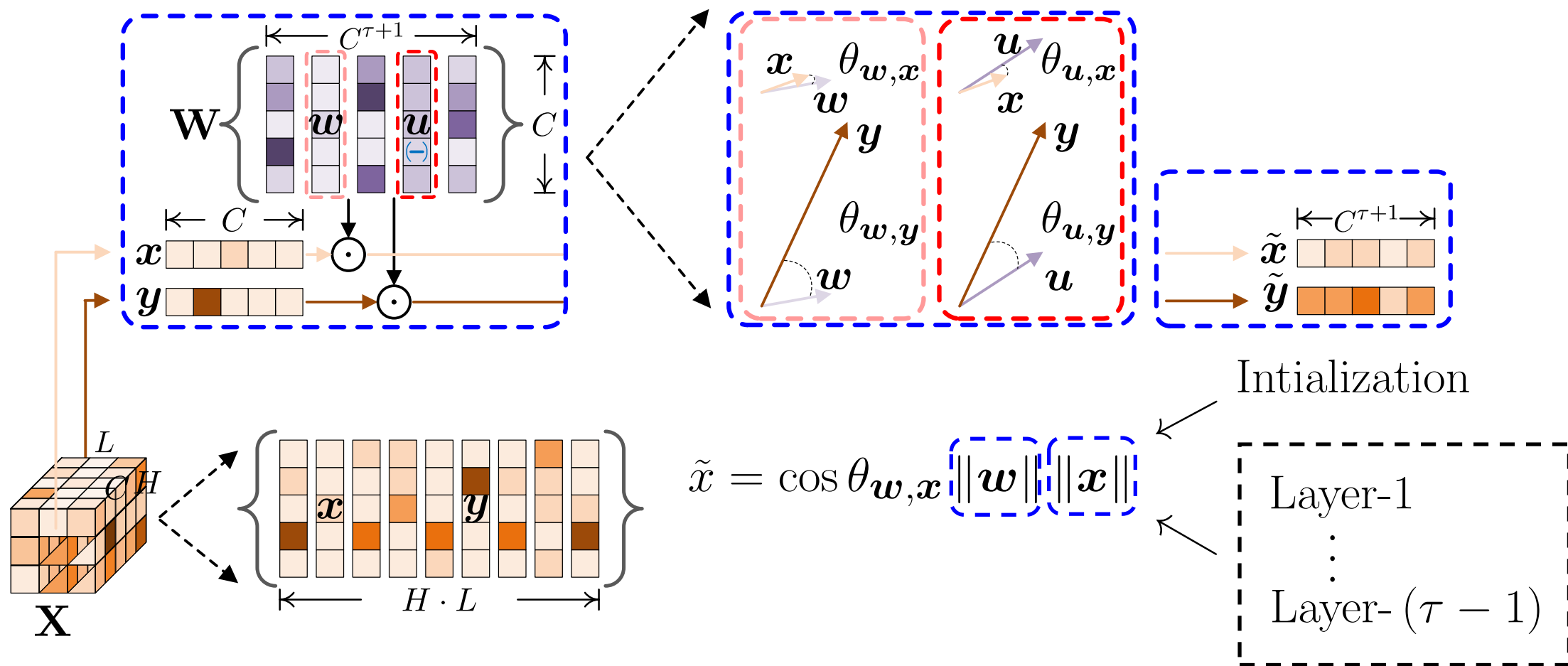
→
Smoothing

$$\rho(\tilde{x}) = \text{sigmoid}(\tilde{x}) .$$



Intuition

- A critical problem: *Mismatched Feature Scoring (MFS)*¹



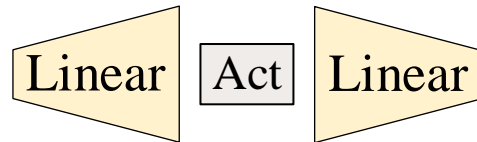
1. Sudong Cai. IIEU: Rethinking Neural Feature Activation from Decision-Making. In *Proc. ICCV*, pages 5796-5806, 2023.

Intuition

- Why AdaShift – Remaining problems in the modeling of IIEU

1. Efficiency of training

$$\phi(\tilde{x}) = \varsigma \left(\frac{\tilde{x}}{\|\mathbf{x}\| \|\mathbf{w}\| + \epsilon} + \nu \right) \cdot \tilde{x}$$



$$\nabla_{\mathbf{w}} s(\mathbf{w}) = \frac{\|\mathbf{w}\|^2 \mathbf{x} - \mathbf{w} \mathbf{w}^T \mathbf{x}}{\|\mathbf{x}\| \|\mathbf{w}\|^3}$$

Expensive FFN with high expansion ratio

2. Extensibility

$$\phi(\tilde{x}) = \varsigma \left(\frac{\tilde{x}}{\|\mathbf{x}\| \|\mathbf{w}\| + \epsilon} + \nu \right) \cdot \tilde{x}$$

$$\tilde{\tilde{x}} := \tilde{x} + \tilde{y}$$

How about if we also consider activating an un-projected feature (unit)?

Can feature and filter norms play a useful role in feature re-weighting?

Intuition of AdaShift

- Rethinking the meaning of feature and filter norms from a Softmax-based classification
 - (Intuition 5.1) Feature and filter norms present local and dataset-level non-local cues, respectively

Pre-conditions: $\mathbf{w}(i)$: The representative filter of the class- i N classes in total
 Let $\mathbf{w}(j)$: The representative filter of an arbitrarily class- j \mathbf{x} is classified as the class- i
 \longrightarrow
 \mathbf{x} : The representative feature of the input (image or pixel) $\forall \mathbf{w}(i) \neq 0, \forall \mathbf{x} \neq 0$

For $i \neq j$
 \longrightarrow

$$\frac{e^{\tilde{x}_i + b_i}}{\sum_{c=1}^C e^{\tilde{x}_c + b_c}} > \frac{e^{\tilde{x}_j + b_j}}{\sum_{c=1}^C e^{\tilde{x}_c + b_c}} \iff e^{\tilde{x}_i + b_i} > e^{\tilde{x}_j + b_j}$$

\longrightarrow

$$\|\mathbf{w}(i)\| \|\mathbf{x}\| \cos \theta_{\mathbf{w}(i), \mathbf{x}} + b_i > \|\mathbf{w}(j)\| \|\mathbf{x}\| \cos \theta_{\mathbf{w}(j), \mathbf{x}} + b_j$$

Intuition of AdaShift

$$\|\mathbf{w}(i)\| \|\mathbf{x}\| \cos \theta_{\mathbf{w}(i), \mathbf{x}} + b_i > \|\mathbf{w}(j)\| \|\mathbf{x}\| \cos \theta_{\mathbf{w}(j), \mathbf{x}} + b_j$$

Let

$$\longrightarrow \alpha = b_j - b_i$$

$$\longrightarrow \|\mathbf{w}(i)\| \cos \theta_{\mathbf{w}(i), \mathbf{x}} - \|\mathbf{w}(j)\| \cos \theta_{\mathbf{w}(j), \mathbf{x}} > \frac{\alpha}{\|\mathbf{x}\|}$$

Case 1: $\|\mathbf{x}\| \gg |\alpha|$

\longrightarrow

Filter norms are influential & Feature norms are not decisive

Case 2: $\|\mathbf{x}\| \ll |\alpha|$

\longrightarrow

Filter norms are influential & Feature norms are influential

Case 3: Others

\longrightarrow

Filter norms are influential & Feature norms matters

AdaShift Prototype

\longrightarrow

Complementary information : tensor-level non-local cues

$$\phi(\tilde{\mathbf{x}}) = \varsigma(\tilde{\mathbf{x}} + \Delta) \tilde{\mathbf{x}}$$

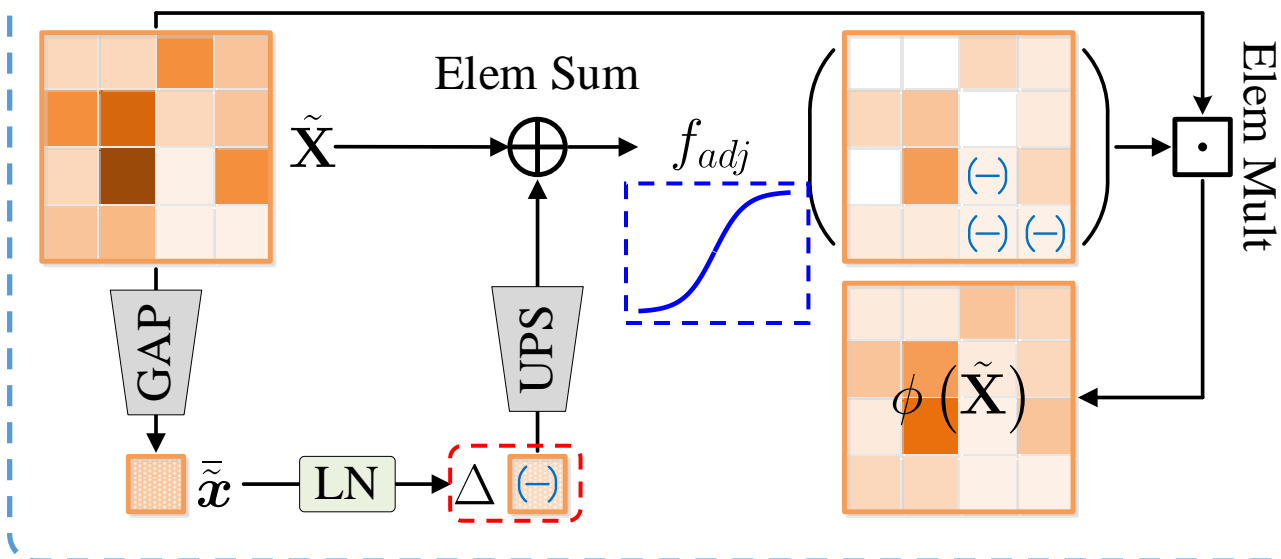
Method

AdaShift Prototype

$$\phi(\tilde{x}) = f_{adj}(\tilde{x} + \Delta) \cdot \tilde{x}$$

Complementary information:
tensor-level non-local cues

AdaShift-B

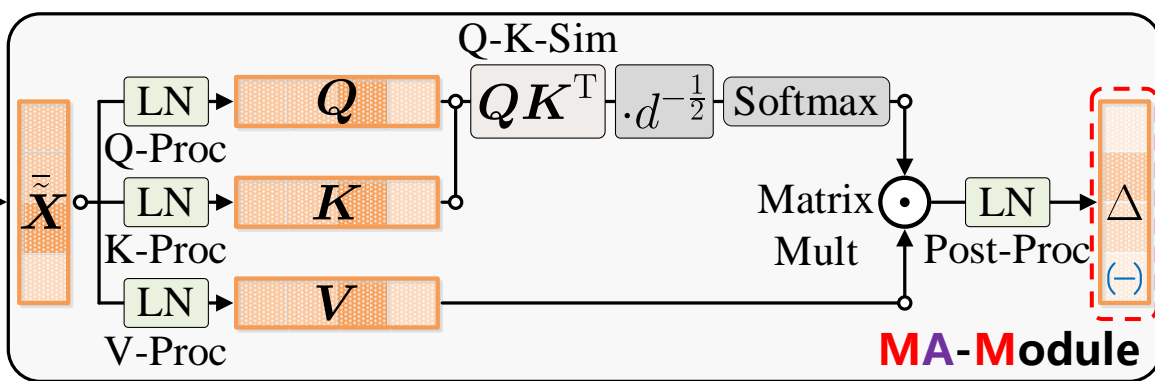


RS Reshape

LAP Local Average Pooling

UPS Upsampling (Broadcast)

$$\Delta = [\text{MA}(\text{avgpool}_{K_H \times K_L}(\tilde{X}))]_c(h_k, l_k)$$



MA-Module

Elem Sum

Elem Mult

AdaShift-MA

Experiment

- Dataset
 - ◆ ImageNet [90]
 - The most popular large-scale visual (image) recognition benchmark dataset
 - ◆ CIFAR(-100) [27]
 - A popular image recognition benchmark dataset of small-size images
 - ◆ COCO [21]
 - A popular large-scale object detection benchmark dataset
 - ◆ KITTI-Materials [23]
 - The benchmark dataset of RGB RMS

[90] J. Deng et al., Imagenet: A largescale hierarchical image database, *CVPR*, 2009

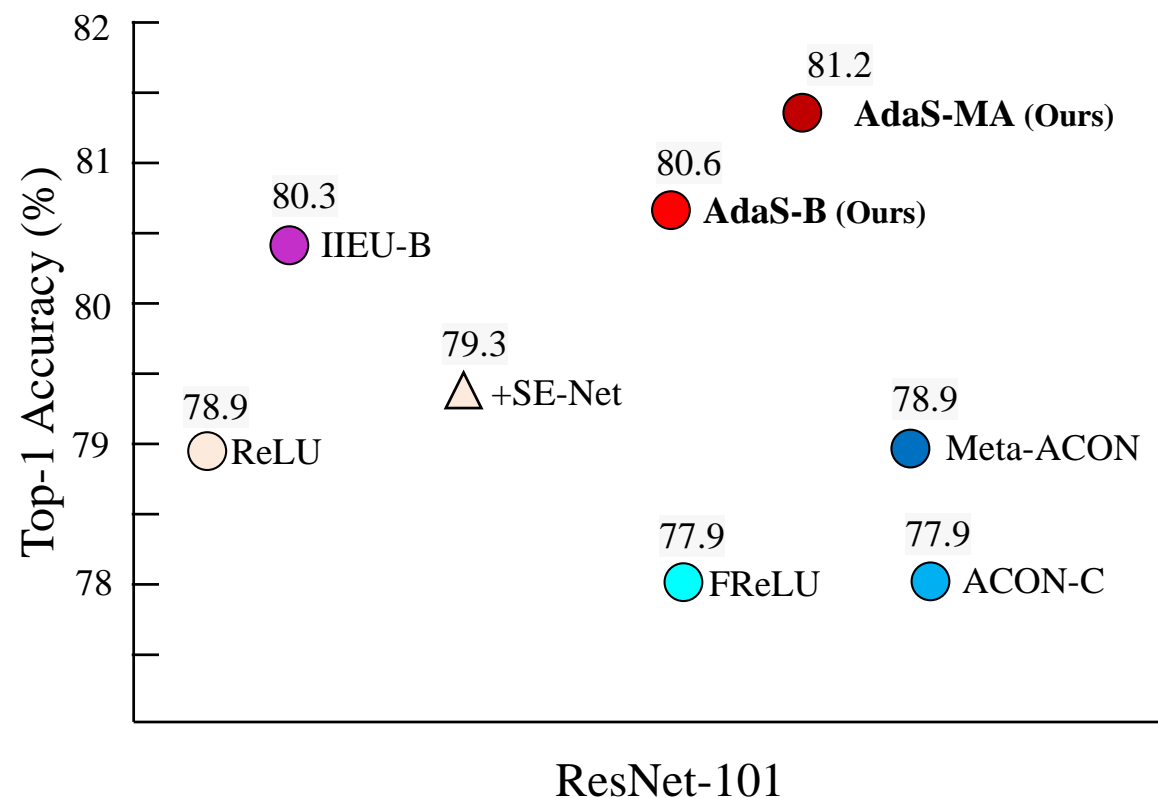
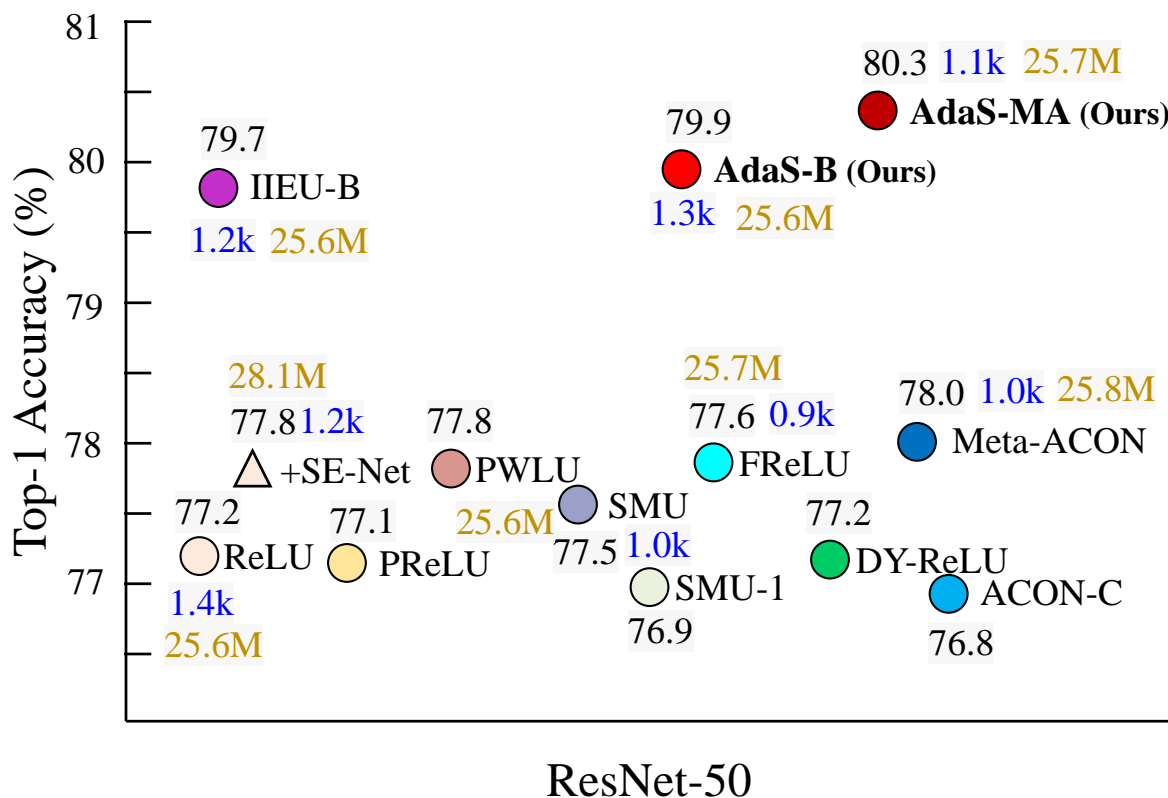
[27] A. Krizhevsky et al., Learning multiple layers of features from tiny images, *Master's thesis*, University of Toronto, 2009

[21] T.-Y. Lin et al., Microsoft coco: Common objects in context, *ECCV*, 2014

[23] Sudong Cai et al., RGB Road Scene Material Segmentation, *ACCV*, 2022

Results

Comparison of AdaShift-B and -MA with prevailing and (other) SOTA activation models on ImageNet using ResNet-50 and ResNet-101 backbones. In the comparison using the ResNet-50 backbone, the *number of parameters* and *throughput* of each model are indicated in **Purple** and **Blue** colors, respectively



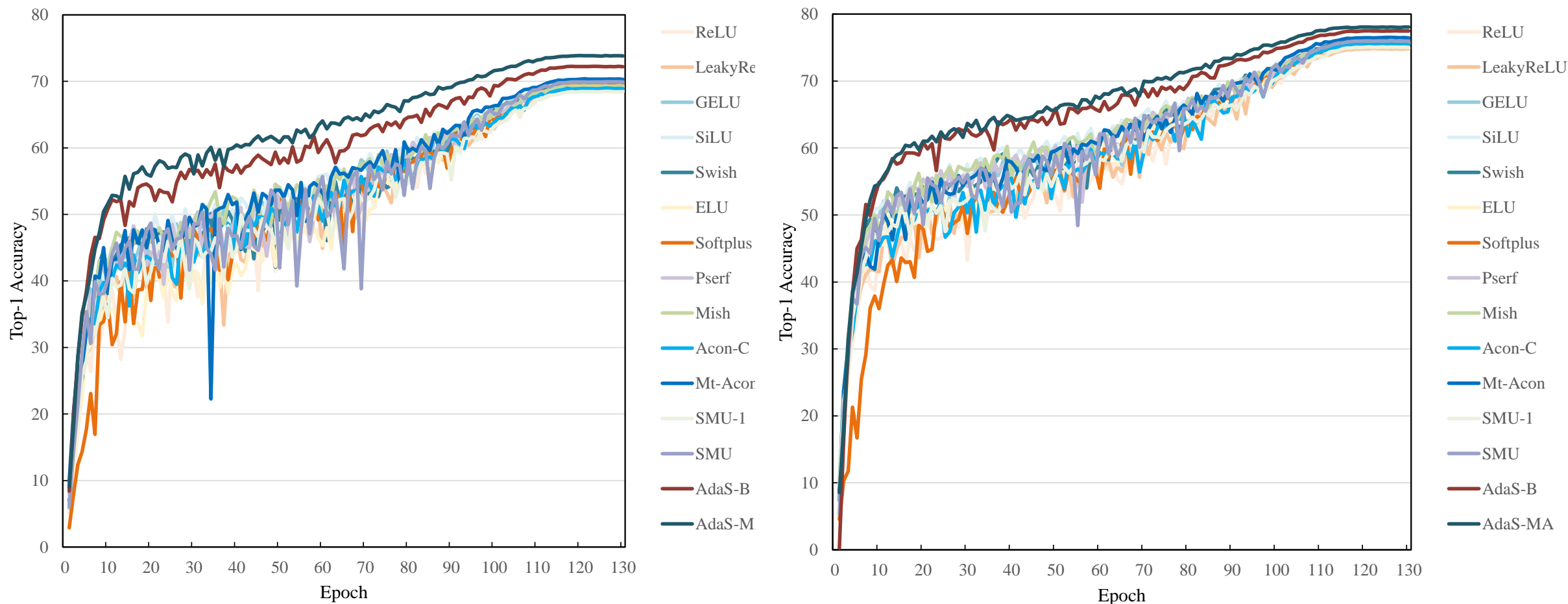
Results

Comparison of AdaShift-enhanced ResNet-50(s) to representative vision Transformer counterparts. “★” denotes the improved ViT trained with an extra regularization. Details can be found in Appendix G.2. (Training with Advanced Recipe)

Network	Activation	Resolution	Train. Epoch	#Params.	FLOPs	Throughput	Top-1(%)↑
ViT-B/16★	GELU	224 × 224	300	86.6M	16.9G	775.6	79.7
PoolFormer-S24	GELU	224 × 224	300	21.4M	3.5G	1144.6	80.3
Swin-T	GELU	224 × 224	300	28.3M	4.5G	1052.2	81.3
ResNet-50	AdaS-B (ours)	224 × 224	300	25.6M	4.1G	1352.8	80.8
ResNet-50	AdaS-Hyb (ours)	224 × 224	300	28.2M	4.2G	1201.6	81.7

Results

The Acc. curves (left) and loss curves (right) of ResNet-14 (Top) and ResNet-26 (Bottom) backbones with different activation models



Gratitude for your time and patience!

AdaShift: Learning Discriminative Self-Gated Neural Feature Activation With an Adaptive Shift Factor

Sudong Cai

Graduate School of Informatics, Kyoto University