Improving Generalization Via Meta-Learning on Hard Samples



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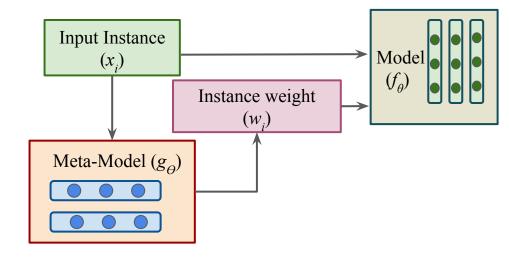


Introduction

- Neural Networks often struggle to generalize well on test distributions including both in-domain and out-of-domain cases.
- The standard ERM optimization has usually been seen as a sub-optimal solution to the exact distributional approximation.
- In this work, we instead formulate a learned re-weighting based formulation for training models, which exploits the fact that models focusing more on the hard examples usually tend to perform better on test distributions.

Instance Conditional Learned Re-weighting

- Train Set: $\{x_i, y_i\}$
- Special Validation Set: (x_i^v, y_i^v)
- $f_{ heta}(\cdot): classifier$
- $\bullet \quad g_{\phi}(\cdot): \; \textit{meta-network}$



Objective:

$$egin{aligned} \phi^* &= rg\min_{\phi} rac{1}{M} \sum_{j=1}^M l(y^v_j, f_{ heta^*(\phi)}(x^v_j)) \ s.t. \ heta^*(\phi) &= rg\min_{ heta} rac{1}{N} \sum_{i=1}^N g_{\phi}(x_i) \cdot l(y_i, f_{ heta}(x_i)) \end{aligned}$$

Idea: Can we improve generalization by using hard samples as target set?

Meta Optimization of Learned Reweighting

A tri-level formulation given overall data $S = \{(x, y)\}_{i=1}^{N+M}$, a splitting function Θ diving S into a target set $\Theta(S)$ and a training set $\Theta(S)^c$:

$$\begin{split} \Theta^* &= \arg \max_{\Theta} \sum_{(x,y)\in\Theta(S)} \ell(y, f_{\theta^*(\phi^*(\Theta),\Theta)}(x)) \\ \text{where } \phi^*(\Theta) &= \arg \min_{\phi} \sum_{(x,y)\in\Theta(S)} \ell(y, f_{\theta^*(\phi,\Theta)}(x)) \\ \text{s.t.} \theta^*(\phi,\Theta) &= \arg \min_{\theta} \sum_{(x,y)\in\Theta(S)^c} \phi(x)\ell(y, f_{\theta}(x)). \end{split}$$

MOLERE(2): A heuristic and an optimization

- Train an ERM classifier on supplied train-val split
- Use model margin to rank-order (train+val) pool
- Pick hardest samples as new val set (LRW-Hard)
 - Additional controls: easy & random validation sets (LRW-Easy, LRW-Random) Ο

$$\begin{split} \Theta^*, \phi^* &= \arg \max_{\Theta} \min_{\phi} \sum_{k=1}^{N+M} \mathbb{1}\{\Theta[k] = 0\} \left(l_{val}(y_k, f_{\theta^*(\Theta, \phi)}(x_k)) - \mathcal{L}_{split} \right) \\ where \quad \theta^*(\Theta, \phi) &= \arg \min_{\theta} \sum_{i=1}^{N} \mathbb{1}\{\Theta[k] = 1\} w_i l_{tr}(y_i, f_{\theta}(x_i)) \quad \begin{array}{l} \mathcal{L}_{split} = CE(\mathbb{P}_{splitter}(z_i|x_i, y_i), \mathbb{I}_{y_i}(\hat{y})) \\ \text{where} \quad \hat{y} = \arg \max \mathbb{P}_{predictor}(y|x_i) \end{split}$$

- Inner objective of bilevel optimization minimizes loss on current validation set
- Outer objective is a minimax optimization
 - Propose a <train,val> split using a splitter $g_{\Theta}(x)$ Propose an instance weight using a scorer $g_{\phi}(x)$ 0
 - 0
 - Splitter aims to maximize validation loss, while reweighter aims to minimize it 0

Frain twice Heuristic

MOLERE: A robust optimization objective

• Given total number of samples $N + M \to \infty$, and $\lim_{N,M\to\infty} \frac{M}{N+M} = \delta$, the objective of MOLERE is equivalent to:

$$\max_{S:|S|=\delta(N+M)} \min_{\theta} \sum_{(x,y)\in S} \ell(y, f_{\theta}(x)).$$

- Thus, in the limit of infinite samples, MOLERE identifies hardest examples and learns a classifier that minimizes error on these samples.
- Also, the above objective is the **dual** of the popular Distributionally Robust Optimization:

$$\min_{\theta} \max_{S:|S|=\delta(N+M)} \sum_{(x,y)\in S} \ell(y, f_{\theta}(x)).$$

MOLERE Algorithm

Algorithm 1 LRWOpt: The Overall One-Shot Algorithm.

Require: θ , Θ , ϕ , learning rates (β_1 , β_2 , β_3), S, N, M. **Ensure:** Robustly trained classifier parameters θ .

- 1: Randomly initialize θ , Θ and ϕ ;
- 2: initialize ge = 0; \triangleright Difference b/w train and val error
- 3: for e=1 to MaxEpochs do
- 4: $S_{tr}, S_{val} = \text{GenerateSplit}(\mathcal{D}, \Theta)$
- 5: **for** b = 1 **to** M//m **do** \triangleright m is the batch size
- 6: $\{(x_i^v, y_i^v)\}_{i=1}^m = \text{SampleMiniBatch}(\mathcal{S}_{val}, m);$
 - $\Theta \leftarrow \Theta \beta_1 \nabla_{\Theta} \sum \left(\mathcal{L}_{split} \ell(y_i^v, f_{\theta}(x_i^v)) \right)$
- 8: $\phi \leftarrow \phi \beta_2 \nabla_{\phi} \sum \left(\ell(y_i^v, f_{\theta}(x_i^v)) \mathcal{L}_{split} \right)$
- 9: **for** j = 1 **to** Q **do**
- 10: $\{(x_i, y_i)\}_{i=1}^n \text{ SampleMiniBatch}(\mathcal{D}_t, n); \\ \theta \leftarrow \theta \beta_3 \nabla_\theta \sum g_\phi(x_i) \ell(f_\theta(x_i), y_i);$
- 12: end for
- 13: **end for**

7:

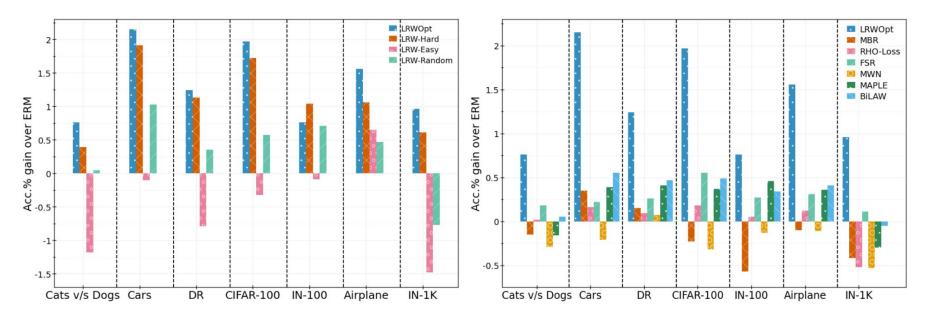
- 14: **if** $\sum \ell(y_i^v, f_\theta(x_i^v)) \sum \ell(y_i, f_\theta(x_i)) < \text{ge then}$ 15: **break**;
- 16: **end if**
- 17: $ge = \sum \frac{1}{M} \ell(y_i^v, f_\theta(x_i^v)) \frac{1}{N} \sum \ell(y_i, f_\theta(x_i))$ 18: end for

Results and Analysis

Robustness on the Benchmark Datasets: In-Distribution

MOLERE v/s the Heuristics

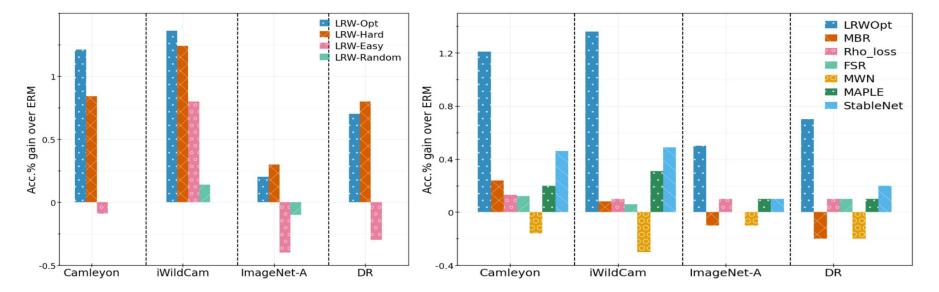
MOLERE v/s existing re weighing methods



Robustness on the Benchmark Datasets: OOD

MOLERE v/s the Heuristics

MOLERE v/s existing re weighing methods



Practical Label Noise Settings and Skewed Label setups

Instance dependent noise:

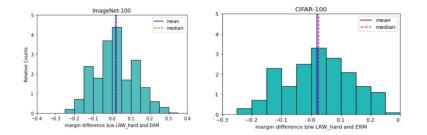
	MWN	FSR	L2R	MAPLE	GDW	Ours
Inst. C-10 Clothing-1M	1075 CARLON AL 400 GEOGRAFI			70.34 71.67	69.12 73.12	

Skewed Label Scenario on CIFAR-100:

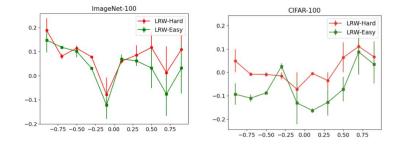
class skew	200	50	10	1
MWN [34] FSR [43] GDW [6]	$ \begin{vmatrix} 40.11 \pm 0.9 \\ 38.04 \pm 0.8 \\ 40.36 \pm 1.0 \end{vmatrix} $	$\begin{array}{c} 48.67 \pm 0.7 \\ 45.12 \pm 0.9 \\ 48.89 \pm 0.8 \end{array}$	$\begin{array}{c} 61.32 \pm 0.6 \\ 58.38 \pm 0.6 \\ 61.67 \pm 0.5 \end{array}$	$\begin{array}{c} 74.23 \pm 0.3 \\ 74.68 \pm 0.2 \\ 74.41 \pm 0.4 \end{array}$
LRWOpt	$ $ 42.33 \pm 0.8	$\textbf{50.77} \pm 0.7$	$\textbf{63.28} \pm 0.8$	$\textbf{75.12} \pm 0.3$

Margin Maximization Via Meta-Learning

Pairwise Margin Delta between MOLERE and ERM: right-skewed with mean/median > 0



Better Margin gain over ERM of the LRW-hard heuristic as compared to the LRM-Easy (as a function of ERM margin)



Thank You!