

Contributions

- SpatialScore**: the most comprehensive and diverse *spatial intelligence benchmark* to date, comprising *~5K challenging samples* spanning *30 distinct tasks*;
- SpatialCorpus**: a *large-scale training resource* with *331K multimodal QA samples* for supervised fine-tuning (SFT) on spatial understanding tasks;
- SpatialAgent**: a *multi-agent system* with *12 perception tools* that supports *Plan-Execute* and *ReAct* reasoning, enabling substantial gains in a *tuning-free manner*;
- Evaluation**: extensive assessments over *49 representative MLLMs* reveal a substantial gap between current models and human-level spatial intelligence.

SpatialScore Benchmark Overview

1. Mental Animation

Question: Which one is the paper after unfolding the punched paper?

Answer: **A.**

5. Object Motion

Question: What direction is the train moving towards?

Answer: **C.**

7. Temporal Reasoning

Question: Facing the door, how to get to the window?

Answer: **B.**

2. Counting

Question: How many chair(s) are in this room?

Answer: **2.**

6. Camera Pose & Motion

Question: Is the camera moving left or right?

Answer: **B. right**

8. View Reasoning

Question: Which side of the white truck is facing the mini post sign?

Answer: **B.**

3. Depth Estimation

Question: The depth of the sine (red point) is 1.1 meters, predict the depth of the bag (blue point).

Answer: **1.0 meters.**

9. Object Size

Question: Can the teddy bear fit left of the media console?

Answer: **Yes.**

4. Object Distance

Question: What is the minimum distance between the wooden table and the bed frame near the camera?

Answer: **1.24 meters.**

10. Object Localization

Question: Detect the speaker (3D box) with format: [x, y, z, x, size, y, size, z, size].

Answer: **A.**



Qualitative Comparison

SpatialAgent-Qwen-ReAct

Question: What is the vertical gap between the refrigerator and the cabinet above it?

Ground Truth: **11.0 centimeters.**

LLaVA-OV-7B: 10 inches ✗
Qwen2.5VL-7B: 30 inches ✗
InternVL3-8B: 15 inches ✗
LLaVA-OV-72B: 12 inches ✗
Qwen2.5VL-72B: 5 inches ✗
InternVL3-78B: 5 inches ✗

SpatialAgent-Intern-ReAct

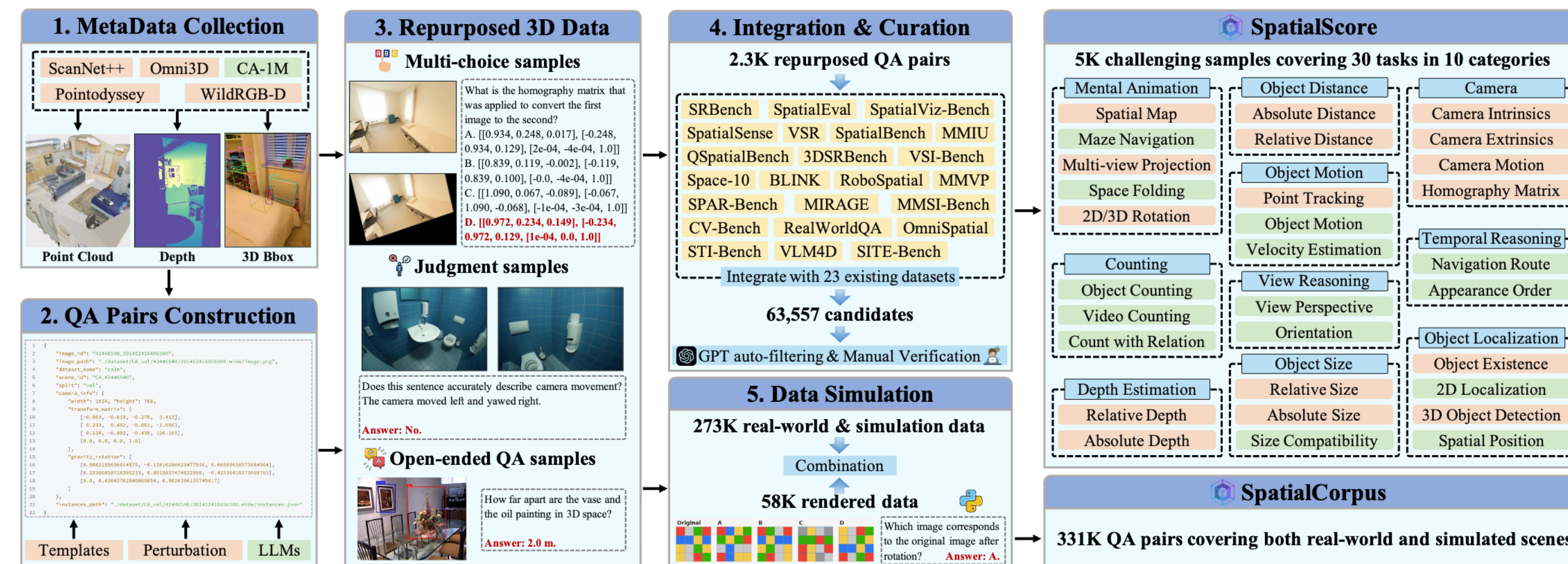
Question: What is the minimum distance between the two stool chairs in the image?

Ground Truth: **15.0 centimeters.**

LLaVA-OV-7B: 1 meter ✗
Qwen2.5VL-7B: 60 cm ✗
InternVL3-8B: 1 meter ✗
LLaVA-OV-72B: 0.5 meters ✗
Qwen2.5VL-72B: 1 meter ✗
InternVL3-78B: 12 inches ✗

Data Construction

Dataset	Publication	Data Types			Input Modalities			QA Formats			#Tasks	#Samples
		Real	Simulated	AIGC	Image	Sequence	Video	MCQ	Yes/No	Open		
QSPatialBench [44]	EMNLP 2024	✓	✗	✗	✓	✗	✗	✗	✗	✓	2	271
SpatialEval [81]	NeurIPS 2024	✓	✓	✗	✓	✗	✗	✓	✓	✗	4	4,635
VSI-Bench [98]	CVPR 2025	✓	✗	✗	✗	✗	✓	✓	✗	✓	8	5,156
RoboSpatial-Home [72]	CVPR 2025	✓	✗	✗	✗	✗	✓	✗	✗	✓	3	350
3DSRBench [56]	ICCV 2025	✓	✗	✗	✓	✗	✗	✓	✓	✗	4	2,772
STI-Bench [42]	ICCV 2025	✓	✗	✗	✗	✗	✓	✓	✗	✗	8	2,064
VLM4D [113]	ICCV 2025	✓	✗	✓	✗	✗	✓	✓	✗	✗	4	1,816
SITE-Bench [88]	ICCV 2025	✓	✗	✓	✓	✓	✓	✓	✓	✗	6	8,068
MIRAGE [47]	NeurIPS 2025	✓	✗	✗	✓	✓	✗	✗	✓	✓	3	1,710
SPAR-Bench [110]	NeurIPS 2025	✓	✓	✗	✓	✓	✓	✓	✓	✗	20	7,211
SpatialViz-Bench [86]	ICLR 2026	✗	✓	✗	✓	✗	✗	✗	✗	✗	12	1,180
MMSI-Bench [103]	ICLR 2026	✓	✓	✗	✗	✓	✓	✓	✗	✗	11	1,000
OmniSpatial [33]	ICLR 2026	✓	✓	✗	✓	✓	✓	✓	✓	✗	50	1,533
SpatialScore (Ours)	CVPR 2026	✓	✓	✓	✓	✓	✓	✓	✓	✓	30	5,025



(a) Data Construction Pipeline of SpatialScore and SpatialCorpus

SpatialAgent Framework

Plan-Execute Paradigm

Question: Compute the homography matrix between the given two images. Select the correct choice.

A: [...][...][...] B: [...][...][...] C: [...][...][...]
D: **[1.12, 0.03, 158.94], [0.14, 0.99, -24.46] [4e-03 4e-05 1.00]**

Plan: Plan: [{"name": "MatchImagesSIFT", "arguments": {"image": "image-0", "image-1": "image-1", "num_keypoints": 1200}}, {"name": "EstimateHomographyMatrix", "arguments": {"image": "image-0", "image-1": "image-1", "num_keypoints": 1200, "ratio_th": 0.75}}]

Execute: MatchImagesSIFT: {'matches': [[[300.07, 626.34], [455.01, 561.02]], [...]]}; EstimateHomographyMatrix: [[1.12, 0.03, 158.95], [0.14, 0.99, -24.10], [4e-03, 4e-05, 1.00]]

Sum: The provided homography matrix from the tool execution is: [[1.12, 0.03, 159.85], [0.14, 0.99, -24.10], [4e-03, 4e-05, 1.00]]

The values in the estimated matrix are very close to those in option D. **Therefore, option D is the correct choice.**

ReAct Paradigm

Question: Consider the real-world 3D location of the objects in the image. Which object is closer to the camera?

(A) bicycle.
(B) **vacuum machine**

Plan: To determine which object is closer, I need to estimate the depth of each object using the EstimateObjectDepth tool.

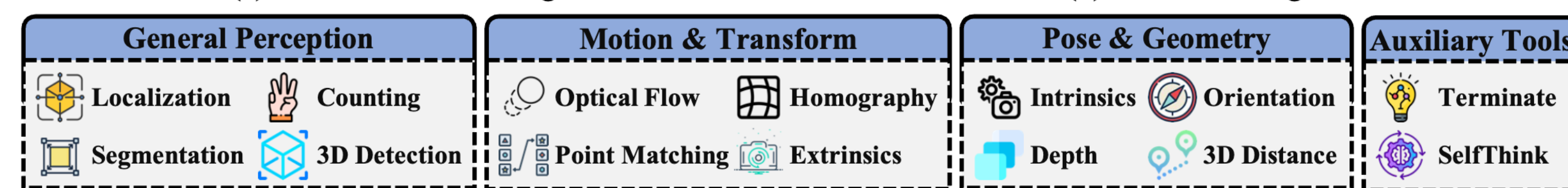
Execute: "action": [{"name": "EstimateObjectDepth", "arguments": {"image": "image-0", "objects": ["bicycle", "vacuum machine"]}}]

Results: [{"object": "bicycle", "depth": 1.5 meters}, {"object": "vacuum machine", "depth": 1.2 meters}] Therefore, the vacuum machine is closer to the camera than the bicycle.

Execute: "action": [{"name": "Terminate", "arguments": {"answer": "(B)"}}, {"name": "Sum": "Based on the above observations, **option (B) is right.**"}

(a) Plan-Execute Paradigm

(b) ReAct Paradigm



(c) SpatialAgent Toolbox

Quantitative Comparison

Methods	Overall	Rank	Mental.	Count.	Depth.	View-Rea.	Obj-Size.	Obj-Loc.	Obj-Dist.	Obj-Mo.	Camera.	Temp-Rea.
Baselines												
Blind GPT-5 (Text-only) [12]	30.62	-	18.79	20.34	29.36	40.81	31.05	45.34	24.20	25.54	32.01	26.47
Chance-level (Random)	28.29	-	23.71	22.80	22.88	31.84	30.29	38.59	24.06	25.06	28.79	28.68
Human-level	86.60	-	96.87	89.72	82.33	92.15	85.18	81.64	78.96	94.46	86.89	84.19
Small-scale models (1B~4B)												
InternVL2.5-1B [15]	31.66	13	30.20	38.42	22.26	32.29	32.29	51.08	25.12	26.02	27.76	25.74
InternVL3-1B [114]	33.03	12	26.85	47.69	24.74	32.06	34.06	57.53	24.02	32.29	25.71	19.85
InternVL3.5-1B [87]	33.55	11	31.10	40.27	33.47	30.72	30.95	53.08	26.72	24.82	29.43	29.41
Qwen3-VL-2B [5]	41.41	5	35.35	52.74	34.64	35.65	49.69	61.69	35.42	38.80	30.59	39.34
Qwen2.5-VL-3B [6]	36.92	8	32.21	46.07	33.07	34.53	38.48	56.53	29.73	37.59	30.59	24.26
SpaceQwen2.5VL-3B [13]	31.25	14	20.81	47.74	22.51	32.96	38.82	39.45	25.13	30.60	29.95	24.26
SpaceThinker-3B [13]	34.47	10	27.96	48.30	34.64	34.08	36.89	44.76	28.07	35.42	28.66	26.84
SpatialThinker-3B [7]	37.16	7	29.75	50.79	37.45	37.22	31.69	58.97	31.87	35.18	30.08	22.79
VST-3B-SFT [101]	47.37	2	25.73	48.45	53.11	45.74	53.02	61.41	42.35	60.48	35.35	50.74
VST-3B-RL [101]	48.04	1	24.61	52.38	51.75	43.72	54.16	61.84	43.03	62.89	38.95	47.43
Spatial-MLLM-4B [91]	42.59	3	33.56	47.61	34.80	43.27	56.16	57.68	40.49	36.39	28.41	53.31
Qwen3-VL-4B [5]	42.52	4	37.81	48.22	37.68	34.75	48.20	59.40	33.40	53.01	34.06	38.24
InternVL2.5-4B [15]	36.18	9	27.52	45.15	41.25	35.65	35.43	57.25	29.23	29.64	29.18	23.53
InternVL3.5-4B [87]	37.81	6	34.23	40.40	40.97	34.75	29.59	60.11	31.15	38.07	30.46	34.19
Middle-scale models (7B~14B)												
LLaVA-1.5-7B [49]	25.32	19	20.58	21.64	29.34	22.42	22.25	47.20	14.43	24.58	27.63	2.21
LLaVA-OneVision-7B [38]	36.57	15	25.50	45.97	38.92	36.32	42.31	56.67	29.01	29.40	32.13	16.18
Qwen2.5-VL-7B [6]	40.53	9	42.06	48.67	43.44	37.00	40.88	57.82	34.02	43.61	28.66	26.84
SpaceR-7B [63]	43.36	6	44.74	51.13	45.31	37.44	48.48	58.39	35.98	45.06	33.03	31.62
VST-7B-SFT [101]	50.06	2	39.37	54.00	53.67	43.05	52.91	63.27	46.44	62.65	39.72	45.96
VST-7B-RL [101]	52.47	1	41.39	54.92	56.80	50.00	55.48	64.56	48.65	63.37	42.80	45.59
SpatialThinker-7B [7]	40.83	8	39.82	49.46	44.41	34.75	41.88	59.40	33.13	44.34	31.36	23.90
SpatialReasoner-8B [57]	36.31	16	36.02	41.21	36.12	36.32	34.63	53.23	28.00	33.73	31.75	26.10
InternVL2.5-8B [15]	39.63	11	40.27	45.85	45.39	35.43	45.25	58.82	34.07	27.71	28.53	28.31
InternVL3-8B [114]	41.57	7	37.81	51.95	39.46	38.79	43.05	64.13	36.02	41.69	29.95	28.31
InternVL3.5-8B [87]	37.75	12	38.48	42.64	41.25	31.39	33.29	60.83	32.27	36.39	32.39	13.60
Qwen3-VL-8B [5]	45.48	3	38.26	50.35	47.12	37.67	52.12	61.12	37.22	55.90	34.19	41.54
LLaMA-3.2V-11B [29]	35.13	17	40.72	47.81	38.96	36.55	25.98	51.94	25.33	33.98	29.05	17.28
LLaMA-3.2V-11B-CoT [95]	37.51	13	28.64	39.71	40.51	35.87	47.98	54.52	31.84	31.77	29.18	25.74
LLaVA-1.5-13B [49]	26.67	18	25.06	25.91	31.52	20.63	23.59	47.63	16.10	26.51	28.15	1.84
SpaceLLaVA-13B [13]	23.97	20	34.23	32.14	26.93	22.65	19.35	36.01	15.13	19.52	15.30	23.16
InternVL3-14B [114]	44.89	4	44.52	53.05	42.92	37.89	48.86	62.84	40.86	43.37	35.35	35.29
InternVL3.5-14B [87]	43.88	5	45.64	46.63	41.66	40.36	46.95	64.56	36.82	42.65	35.60	29.04
Kimi-VL-16B-A3B [76]	40.10	10	29.08	53.32	38.25	41.03	45.17	59.11	35.85	43.61	27.38	25.74
Kimi-VL-A3B-Thinking [76]	37.06	14	30.20	40.70	32.03	35.43	45.74	52.37	28.22	32.77	33.16	33.82
Large-scale models (30B~78B)												
Qwen3-VL-30B-A3B [5]	50.71	3	46.31	58.86	48.49	47.98	56.52	66.43	40.73	59.52	39.20	45.59
Qwen2.5-VL-32B [6]	47.23	8	45.41	50.38	52.28	39.46	49.25	61.84	40.35	56.14	40.23	29.04
Qwen3-VL-32B [5]	54.11	2	43.40	61.16	51.80	50.22	59.53	69.58	50.94	66.75	41.26	47.79
InternVL2.5-38B [15]	45.60	10	43.62	52.98	52.71	37.67	50.47	62.70	39.16	50.84	35.09	21.69
InternVL3-38B [114]	48.95	5	45.64	58.06	49.10	42.15	50.61	67.58	41.04	57.83	39.46	33.82
InternVL3.5-38B [87]	45.74	9	40.27	43.98	48.58	40.13	52.95	62.84	39.31	48.19	39.72	29.04
LLaVA-OneVision-72B [38]	43.29	11	37.58	51.57	51.45	38.57	50.24	62.12	31.84	37.59	38.43	19.49
Qwen2.5-VL-72B [6]	48.42	7	53.69	49.49	56.23	36.10	50.91	62.55	38.42	59.52	42.93	22.43
InternVL2.5-78B [15]	48.71	6	51.45	54.15	54.61	43.50	53.68	62.84	41.67	52.05	39.20	25.74
InternVL3-78B [114]	50.67	4	50.34	59.19	48.74	45.74	50.32	65.71	42.50	60.48	41.52	43.75
Qwen3-VL-235B-A22B [5]	56.63	1	57.27	65.19	54.04	52.47	59.90	70.01	50.40	69.40	42.80	49.63
Proprietary Models (Commercial APIs)												
Claude-4.5-Sonnet [4]	45.68	4	51.01	49.67	47.33	39.91	54.08	53.66	38.68	46.99	36.12	41.18
Gemini-2.5-Pro [18]	56.37	3	73.29	64.04	51.15	46.41	58.24	66.52	46.93	57.84	48.78	56.25
Gemini-3-Pro [28]	60.12	1	70.40	62.99	58.15	62.44	60.02	64.20	49.50	71.12	51.37	59.93
GPT-5 [62]	58.13	2	78.08	57.59	55.13	54.04	59.22	67.39	45.01	57.11	50.90	62.13